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SPACECRAFT OPERATIONAL TRAJECTORY ALTERNATE 1. LUNAR ORBITAL MISSION. MISSICN PROFILE FOR A MISSION LAUNCHED 21 DECEMBER 1968 (NASA)

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APOLLO MISSION C' SPACECRAFT OPERATIONAL TRAJECTORY ALTERNATE 1, LUNAR ORBITAL MISSION VOLUME I - MISSION PROFILE FOR A MISSION LAUNCHED DECEMBER 21, 1968

> By Lunar Mission Design Section Lunar Mission Analysis Branch

> > October 25, 1968

MISSION PLANNING AND ANALYSIS DIVISION NATIONAL AERONAUTICS AND SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS

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APOLLO MISSION C' SPACECRAFT OPERATIONAL TRAJECTORY

ALTERNATE 1, LUNAR ORBITAL MISSION

VOLUME I - MISSION PROFILE FOR A MISSION

LAUNCHED DECEMBER 21, 1968

By Lunar Mission Design Section

1.0 SUMMARY AND INTRODUCTION

The spacecraft operational trajectory for Mission C' - Alternate 1, is composed of four volumes which summarize the spectrum of missions for a 2-month launch period (December 1968 and January 1969). Other than this volume, Volume I, the operational trajectory document consists of the following volumes.

- 1. Volume II Trajectory Parameters for a Mission Launched December 21, 1968: Listing of significant trajectory parameters computed at selected time points during each phase of the same typical mission described in this volume. It also contains a tracking acquisition and loss table. (MSC Internal note no. 68-FM-253.)
- 2. Volume III Summary of Missions for December 1968 Launch Window: Summarizes missions for specific launch azimuths (72°, 81°, 90°, 99°, 108°) and summarizes selected parameters as a function of launch azimuth (72° through 108°) for each daily window (December 20 through December 27). (MSC Internal note no. 68-FM-254.)
- 3. Volume IV Summary of Missions for January 1969 Launch Window: Summarizes missions for specific launch azimuths (72°, 81°, 90°, 99°, 108°) and summarizes selected parameters as a function of launch azimuth (72° through 108°) for each daily window (January 18 through January 24). (MSC Internal note no. 68-FM-255.)

Although this volume of the operational trajectory document presents a mission profile for a December 21, 1968 launch, 72° launch azimuth, first injection opportunity, the profile should be interpreted as being typical of the lunar missions planned during both the December and January windows. Therefore, the guidelines and constraints, the launch

window description (summarized in table I), and tracking ship placement (discussed in section 6.0) apply to the spectrum of missions summarized in Volumes III and IV.

The missions were designed for a daylight launch and reasonable lighting in the Apollo zone. In the initial design "target sites" (some of which are Apollo landing sites) and approach azimuths to these sites were selected for each launch date to provide favorable trajectory characteristics. Lunar orbit inclination, inclination of the free-return trajectory, and propellant reserves were the main parameters considered in this initial design.

Table I shows the target site designation, the selected approach azimuth, and lighting conditions at each site for each launch date. Table II shows the designation and location of the sites. In general, the lighting is not favorable at the target sites for the landmark tracking objectives. Therefore, lunar landmarks are being selected for each launch date in a longitude region of acceptable lighting (approximately 5° elevation with respect to the local horizontal). These landmarks are not yet available.

It is emphasized that the launch vehicle operational trajectory (ref. 2) published by MSFC is the official source for LV data. Data related to the launch and translunar injection is included in this document because it is approximately correct and is informative.

A mission lighting document is being published which summarizes the lighting for the major mission phases for both monthly windows (ref. 1).

The translunar injection tracking ship section of this document was prepared by Mrs. M. B. Vick of the Mission Design Section of the TRW Systems Group.

The entry phase was computed and documented by the Reentry Studies Section of the Landing Analysis Branch, Mission Planning and Analysis Division.

As revisions for this basic profile evolve, this document will necessarily be revised.

2.0 ABBREVIATIONS

A/RIA Apollo Range Instrumentation Aircraft center of gravity c.g. CMcommand module CSM command and service modules DSKY display keyboard EMS entry monitoring system EPO earth parking orbit EOI earth orbit insertion g.e.t. ground elapsed time from lift-off GNCS guidance and navigation control subsystem IGA inner gimbal angle spacecraft inertial measurement unit **IMU** ISP specific impulse L/D lift-to-drag ratio liquid hydrogen LH2 lunar module LMLOI lunar orbit insertion LOI(1) lunar orbit insertion into 60- by 170-n. mi. orbit LOI(2) lunar orbit circularization burn - from 60 by 170 to 60 by 60 n. mi. LPO lunar parking orbit

liquid oxygen

LOX

LTAB lunar test article (B)

LV launch vehicle

MCC midcourse correction

MGA middle gimbal angle

MSFC Marshall Space Flight Center

MSFN Manned Space Flight Network

NPV nonpropulsive vent

OGA outer gimbal angle

PV propulsive vent

RCS reaction control system

REFSMMAT transformation matrix from inertial to

stable member (IMU)

SC spacecraft

SCT scanning telescope

S-IVB launch vehicle third stage

SLA spacecraft LM adapter

SM service module

SPS service propulsion subsystem

 ${
m TB}_7$ time base seven - initiated at TLI cutoff

TEI transearth injection

Tig time of ignition

TLI translunar injection

3.0 PRIMARY GUIDELINES AND CONSTRAINTS

The design of the mission and the resulting launch windows were based on the following primary guidelines and constraints:

- a. Launch will occur between 30 minutes prior to sunrise and 30 minutes after sunset.
- b. The launch azimuth spread will be from 72° to 108° unless other constraints, such as daylight launch, restrict the azimuth range.
- c. Launches will be planned on consecutive days throughout the available monthly windows.
- d. The first TLI injection opportunity will occur on the second earth parking orbit, and the second opportunity on the third orbit.
 - e. TLI will be targeted for a free-return circumlunar trajectory.
 - f. All CSM/SPS maneuvers will utilize external AV guidance.
- g. LOI will be performed in two stages with the first burn, LOI(1), resulting in a 60- by 170-n. mi. ellipse and the second, LOI(2), circularizing the orbit at 60 n. mi. two revolutions later.
- h. The lunar orbit geometry will be chosen such that passage over known lunar landmarks will occur with no significant penalty in SC performance.
- i. Approximately six unperturbed (no translation maneuvers) lunar orbits will be available for tracking and navigation. A total of ten orbits will be planned allowing two orbits for post-LOI activities and two orbits for pre-TEI activities.
 - j. TEI will be targeted to a landing longitude of 165° W.
 - k. Transearth return inclination will be limited to a maximum of 40°.
 - 1. Entry range will be 1350 n. mi. (relative range).
- m. Transearth entry speed will be limited to a maximum of 36 323 fps (inertial). This corresponds to a minimum transearth flight time of approximately 50 hours.
- n. The transearth trajectory will be targeted to an entry path angle of -6.26° . (It should be noted that this guideline is incompatible with a recent decision to target nominally to a steeper flight-path angle, i.e., -6.48° . The steeper targeting will be reflected in the first revision of this document.)

4.0 LAUNCH WINDOW DESCRIPTION

Three constraints determined the daily launch windows and translunar injection window as they are currently defined within the December and January launch months.

- a. Free-return circumlunar constraint.
- b. Acceptable lunar lighting within the Apollo zone.
- c. Daylight launch (30 minutes prior to sunrise 30 minutes after sunset).

The daily launch window for a specified site is determined by the acceptable lighting range at that site coupled with the free-return constraint.

The duration of a daily window is restricted by the daylight launch constraint on certain days in both the December and January windows.

The Pacific injection window for both December and January is dictated by the daylight launch requirement coupled with acceptable lighting within the Apollo zone. Table I shows the opening and the duration of the daily windows for December and January. The times shown are related to the total azimuth spread $(72^{\circ}$ to $108^{\circ})$ and do not reflect the daylight launch constraint. The duration of the total window for all dates is approximately $4^{h}35^{m}$.

Figures 1(a) and 1(b) are plots of launch azimuth versus launch time and show how certain daily windows in December and January are restricted by the daylight constraint.

On December 20 [fig. l(a)] the first acceptable azimuth is approximately 80° , the window duration is about $4^{h}0^{m}$, and opens at about $6^{h}53^{m}$ e.s.t. The windows for the following dates open at successively later times until on December 27, the first opportunity is about $16^{h}45^{m}$ e.s.t.

On December 25, 26, and 27 the windows are restricted at the end of the azimuth spread. On the 25, the last launch azimuth available is 102° and the duration of the window is $4^{h}09^{m}$. On December 26 the last azimuth is 89° and the duration is $2^{h}44^{m}$. On December 27, the last azimuth is 78° and the duration of the window is $1^{h}15^{m}$.

In the January window, none of the openings are restricted by daylight launch [fig. 1(b)], but the closing of the January 23 and 24 windows are restricted as follows: On January 23, the last launch azimuth available is about 96° and the window duration is $3^{h}50^{m}$. On January 24, the last launch azimuth available is about 83° and the window duration is $2^{h}35^{m}$.

In the above description of the launch windows the only constraint discussed in detail was daylight launch. Other considerations may further restrict the windows such as lighting for particular phases, possible earth landing for the free-return circumlunar trajectories, and translunar injection coverage. These considerations are being studied and the results will be published at a later date.

5.0 OPERATIONAL MISSION PROFILE DESCRIPTION

This section summarizes a mission profile for a December 21, 1968 launch date. The burn times, propellants used, and most mission phase times are typical of the lunar orbital missions planned for the December and January launch windows, which are summarized in Volumes III and IV.

The profile is concisely presented in table III. In this section, major events, spacecraft performance characteristics, and significant trajectory parameters are described in detail for each phase.

In the design of the spacecraft operational mission, the LV mission phases were simulated independent of the exact LV operational trajectory. The trajectory data presented here for the LV mission phases were simulated with LV data received from the MSFC in a previous intercenter targeting exercise. No attempt was made to exactly duplicate the LV operational mission, and the information for the LV phases will differ from that in the official trajectory document (ref. 2). The parameters for the LV mission phases should be considered as typical values only.

The data presented in tables IV and V apply to the missions throughout the window. Table IV, the spacecraft weight and engine characteristics, were taken from reference 3. Table V lists the assumed mission-independent expendables. These data and spacecraft weights in table IV were used to determine mission fuel reserves and weight histories.

Tables VI and VII give the mission radar and shadow timelines for all mission phases except launch. The radar acquisition and termination data are presented for both 0° and 5° minimum elevation angles. The tracking information in table VI is presented only for the selected launch azimuth (72°) and the first injection opportunity^a.

^aGeneral information for the 72° through 108° launch azimuth range for three earth parking orbits is presented in references 4 and 5. Tracking information for the launch phase 72° through 108° is given in reference 6. These data were derived using now outdated LV trajectories but are still useful as information.

5.1 Earth Launcha

The launch time for this mission was determined to provide an optimized injected payload to support two injection opportunities. It is emphasized that the launch time, in particular, differs slightly (a matter of seconds) from the official launch time in the MSFC LV operational trajectory.

To provide a daylight launch and acceptable lighting in the Apollo zone, the mission was designed for a Pacific injection. The launch is summarized as follows:

Date, month, day	December 21, 1968
Time, hr:min:sec, e.s.t	07:50:59.7
Azimuth, deg	72
Location (Cape Kennedy, Complex 39A)	
Latitude	28°36'30.32"
Longitude	279°23'45.12"

5.2 Earth Parking Orbita

Insertion into EPO occurs at 00:11:19.7 g.e.t. The insertion conditions are:

Insertion location

Latitude, deg	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	32.7
Longitude, deg .		•	•	•	•	•	•	•	•		•	•	•		•				- 54.3
Altitude, n. mi.	•	•	•	•		•	•			•	•	•							103.3
Inclination, deg .																			32.6

The insertion ship positioned at 25° N latitude and 49° W longitude tracks the vehicle for approximately 4 minutes (0° minimum elevation angle) after insertion. A ground track of the EPO phase is given in figure 2(a).

^aThe parameters for this phase are approximate and are presented for information only. The official source for this phase is the MSFC launch vehicle operational trajectory (ref. 2).

The LV maintains local horizontal attitude throughout the EPO phase except for an inertial hold of about 10 seconds immediately following EPO insertion. The total time spent in EPO is 2^h39^m .

5.3 Translunar Injection^a

The TLI burn occurs over the Pacific ocean during the second revolution in EPO:

TLI burn initiation, hr:min:sec, g.e.t	2:50:31.2
Latitude, deg	9.6
Longitude, deg	- 165 . 9
TLI cutoff:	
Latitude, deg	21.1
Longitude, deg	-144.5
Altitude, n. mi	173.6
Flight-path angle, deg	7.5
Inertial velocity, fps	35 582
Burn duration, sec	311.5
S-IVB propellant used, lb	151 000.
Plane change, deg	2.6

TLI is initiated in darkness and the vehicle enters sunlight approximately midway through the TLI burn.

Coverage for the major part of the burn is provided by Hawaii, which acquires shortly after ignition. Additional support of the burn and preignition sequence is supplied by one of the injection ships (table VIII).

^aThe parameters for this phase are approximate and are presented for information only. The official source for this phase is the MSFC launch vehicle operational trajectory (ref. 2).

5.4 Free-return Circumlunar Trajectory

Free-return touchdown is near the western coast of Africa. A water landing can be insured by applying a corrective maneuver at an acceptable time during either the translunar or transearth coast phases of the circumlunar trajectory. The trajectory is characterized by the following:

Pericynthion

Time, hr:min:sec, g.e.t	69:09:29.4
Altitude, n. mi	60.2
Latitude, selenographic, deg	- 9.1
Longitude, selenographic, deg	-174.8
Return vacuum perigee altitude, n. mi	16.4
Transit time from TLI to earth perigee, hr:min:sec	133:29:35
	126.05.19.0
Time, hr:min:sec, g.e.t	130:25:10.2
Altitude, n. mi	65.8
Latitude, deg N	20.7
Longitude, deg W	37.7
Inclination, deg	28.4
Touchdown:	
Longitude, deg W	16.7
Latitude, deg N	10.9

5.5 Posttranslunar Injection Events

A summary of the major events from TLI cutoff through LOX blowdown is given in table IX. In determining the separation attitude maneuver (TB $_7$ -plus-900 seconds), the sun was constrained to between 32° and 90° of the LV +X-axis. This provides over-the-shoulder lighting and avoids any CSM shadow on the S-IVB for the station keeping position. The SC event times on board will be referenced to TLI ignition (column 1 of table IX) and the LV event times to TB $_7$. Therefore, the SC event times will vary with respect to TB $_7$ as TLI burn time varies. The SC maneuver times referenced to TB $_7$ in the table assumed a 300-second TLI burn time.

The purpose of the evasive maneuver at TB₇-plus-2400-seconds is to decrease the probability of S-IVB recontact and to avoid the ice particles expected to be expelled by the S-IVB during the LOX dump (TB₇-plus-7920-seconds). The magnitude of the evasive maneuver is 1.5 fps and requires approximately a 8-second, 4-jet RCS burn.

The direction of the evasive maneuver has not yet been determined but several maneuvers are being investigated. In choosing the ΔV direction, consideration will be given to:

- 1. SC and LV relative positions during the LOX blowdown.
- 2. LV and SC communications requirements.
- 3. Midcourse ΔV requirements.
- 4. Visual monitoring of the S-IVB during the blowdown.

It should be noted that the station keeping position is maintained for approximately 13 minutes. This time could be easily changed, since the period from 1610 to 3600 seconds (TB $_7$) is relatively void of activity.

The S-IVB assumes a local horizontal position for the LOX blowdown, with the +X-axis retrograde with respect to the direction of motion. The magnitude of the ΔV resulting from the LOX dump is expected to be approximately 90 \pm 18 fps.

The LOX dump maneuver is designed to reduce the probability of SC recontact with the S-IVB and also to avoid S-IVB impact with the earth or moon. Nominally the LOX dump maneuver will result in a "sling-shot" trajectory; the S-IVB passes behind the trailing edge of the moon and is accelerated by the lunar gravitational field. The result is a heliocentric orbit which avoids either earth or lunar impact.

5.6 Translunar Coast

A ground track of the translunar coast phase is given in figure 2(b), and a time history of altitude for the first 4 hours of coast is provided in figure 3.

Passive thermal control attitude will be maintained throughout most of the translunar coast phase. A detailed timeline for the entire coast phase is currently being defined and will be published later.

Four midcourse correction maneuver points have been defined for the translunar coast phase with corresponding ΔV threshold values. The corrections will be performed if the predicted midcourse ΔV is greater than the threshold values. The times of these maneuver points and threshold values are as follows:

l.	TLI +	6 hours	•		•		•	•		•	•	•		•	3	fps
2.	TLI +	25 hours	•		•	•							•		1	fps
3.	LOI -	22 hours	•	•	•	•	•	•	•	•		•	•		1	fps
),	TOT	8 houng													٦	fne

The maneuvers are GNCS-controlled using external ΔV guidance. Unless gimbal lock problems occur, the pad IMU alignment (REFSMMAT) will be used for the first three maneuvers and the LOI(2) preferred REFSMMAT for the last maneuver.

Preliminary dispersion analyses indicate that only three MC maneuvers will probably be required; (1), (2), and (4) or, (1), (3), and (4). It also appears that the 120 fps ΔV allowance used in the generation of the operational mission (table V) is somewhat conservative. More detailed MC information including the targeting procedures is contained in reference 6.

The CSM remains in sunlight during the entire translunar coast phase (table VI). The duration of the phase is $66^{\rm h}12^{\rm m}$.

Altitude above the lunar surface for the last 10 hours of translunar coast is provided in figure $^{\downarrow}4$.

5.7 Lunar Orbit Insertion

The LOI burn (described below) is designed to insert the CSM into approximately a 60- by 170-n. mi. LPO. Figure 5 provides a time history

of trajectory parameters during the burn. The burn was simulated with the external ΔV guidance.

LOI initiation:

Time, hr:min:sec, g.e.t	69:07:29.2
Altitude, n. mi	68.5
Selenographic latitude, deg	-7. 2
Selenographic longitude, deg	- 165.3
Burn duration, min:sec	4:05.8
Inertial burn arc, deg	16.3
Plane change, deg	2.4
ΔV, fps	2 991
SPS propellant used, lb	16 045
LOI burnout (Start LPO):	
Time, hr:min:sec, g.e.t	69:11:35.0
Altitude, n. mi	59.3
Selenographic latitude, deg	-10.0
Selenographic longitude, deg	178.4
Selenographic inclination, deg	167.7
Period of LPO, hr:min:sec	2:08:42
Altitude of pericynthion of LPO, n. mi	59.0
Altitude of apocynthion of LPO, n. mi	168.9

The preferred IMU alignment for the lunar orbit circularization burn LOI(2), was used for the LOI burn as well as for the TEI burn. The CSM is aligned heads-down and the engine is gimballed to account for the c.g. offset.

The target loads for the LOI burn are given in table X. More detailed information about the burn, including reset points, navigation updates, ignition gimbal angles, etc., is given in the "C Prime Simulator Data Package" (ref. 7).

The LOI burn parameters presented below were computed without simulating the SPS thrust buildup and tailoff. The effect of these, however, is reflected in the burn parameters presented in the simulation data package (ref. 7).

5.8 Lunar Orbit Circularization [LOI(2)]

A coplanar circularization burn is performed to place the CSM in approximately a 60-n. mi. circular LPO after two revolutions in the 60- by 170-n. mi. orbit. The target altitude of the orbit (60 n. mi.) is measured relative to the lunar target site (table II), and not to the mean lunar radius.

The burn is initiated near pericynthion of the second revolution. The preferred IMU alignment is used, and the CSM is orientated headsdown. More detailed information is given in reference 7. The characteristics of the burn are:

Circularization burn initiation:

Time, hr:min:sec, g.e.t	73:30:52.8
Altitude, n. mi	59.0
Selenographic latitude, deg	-10.8
Selenographic longitude, deg	169.6
Burn duration, sec	9.7
Inertial burn arc, deg	.5
ΔV, fps	138.5
SPS propellant used, lb	633.8

5.9 Lunar Orbit Coast

The LOI burn results in a 60- by 170-n. mi. elliptical lunar parking orbit. Near the end of the first revolution, general lunar photography is performed. Two revolutions, or abour 4 hours after LOI, the circularization burn is performed to place the CSM in a 60-n. mi.

circular orbit which will pass over the target site on the seventh revolution. On the first revolution after circularization (revolution 3). landmark training photography is performed on the approach to the target site. On the following sunrise, vertical stereo photography is initiated for most of the terminator to terminator pass. Just prior to the approach to the sunset terminator on revolution 4, a general landmark evaluation is made using the SCT. Beginning with revolution 5, the landmark tracking exercises are initiated. These include tracking of landmarks or control points on the back side of the moon and pseudo-landing site sightings near the Apollo landing sites. Two of these sightings are performed on revolutions 5 and 6 (one backside control point and one pseudo-landing site). On revolutions 7 and 8 three sightings are made on control points and one on the pseudo-landing site. This completes the landmark tracking exercises. On the sunrise following the last pseudo-landing site sighting, vertical stereo photography is performed from the terminator to terminator (into revolution 9). The remainder of revolutions 9 and 10 are devoted primarily to TEI preparation. TEI is performed near the end of revolution 10 or about 20 hours after LOI.

5.10 Transearth Injection

TEI occurs $19^{\rm h}52^{\rm m}$ after LOI. A time history of significant parameters during the burn is provided in figure 6. The burn was nominally targeted for an 82-hour transearth flight time. However, it may be desirable to reduce the flight time by 24 hours since no known constraints would be violated. Shorter flight times have been investigated and found acceptable in terms of ΔV requirements and entry conditions. The additional ΔV required to return 1 day early for the mission is approximately $69^{\rm h}$ fps. This additional ΔV results in a propellant penalty of approximately 2293 lb, the flight time 57.5 hours. Note that both burns occur on the back side of the moon. Trajectory parameters associated with both flight times are presented below.

The preferred IMU alignment for the circularization burn [LOI(2)] again was used for the TEI burn. Additional information concerning the nominal TEI (82-hour flight time) is contained in reference 7.

The characteristics of the nominal TEI burn and the burn after a one-day-earlier return are listed on the following page:

Nominal	One day early		
89:04:01.9	89:15:06.6		
- 2.95	-8.76		
- 151.0	177.5		
171.3	206.4		
2 837.8	3 531.7		
11 180.4	13 473.3		
.2	1.5		
Burnout			
3.0	3.0		
61.2	59.9		
-5.1	-10.8		
-161.7	163.8		
36 070.9	36 218.7		
	89:04:01.9 -2.95 -151.0 171.3 2 837.8 11 180.4 .2 3.0 61.2 -5.1 -161.7		

5.11 Transearth Coast

A ground track of the transearth coast phase (for the nominal TEI) is provided in figure 2(d). Altitude above the lunar surface for the first 10 hours of transearth coast is provided in figure 7. The flight time from TEI cutoff to entry interface is 81^h59^m .

As in the translunar coast phase, four MCC maneuver points have been defined:

- 1. TEI + 10 hours
- 2. TEI + 29 hours
- 3. Entry interface 29 hours
- 4. Entry interface 2 hours

For considerably shorter flight times such as that resulting from a return 1 day early (see section 5:10), only three midcourse maneuver points are defined:

- 1. TEI + 8 hours
- 2. TEI + 30 hours
- 3. TEI 2 hours

These midcourse maneuvers are controlled by the GNCS using external ΔV guidance.

Unless gimbal lock is encountered, the REFSMMAT for the LPO circularization burn [LOI(2)] will be used for the first three maneuvers and the entry REFSMMAT for the last maneuver. For shorter flight times the LOI(2) REFSMMAT will be used for the first two and the entry REFSMMAT for the last.

A detailed timeline for the entire transearth coast phase is now being defined. This will define the attitude requirements for navigation sightings, communications, and thermal control. The complete attitude timeline will be published later.

Altitude versus time for the last 10 hours of transearth coast is provided in figure 8. CSM separation occurs 15 minutes prior to entry interface.

The vehicle remains in sunlight except for approximately the last 25 minutes of the transearth coast phase (table VII). S-band communications is lost (above 5° elevation) at approximately 3 minutes prior to entry interface (table VI). Additional coverage will be provided by the entry and injection tracking ships prior to and during entry.

5.12 Entry

The entry phase of the operational trajectory was simulated with the Apollo reentry simulation (ARS) program in six-degrees-of-freedom. Three-degrees-of-freedom trajectories were used to determine the CM maneuver footprint. Table XI shows the REFSMMAT and gimbal angles for entry.

The CM weight, c.g. position in the Apollo coordinate system, and moments and products of inertia (ref. 8) for the reentry interface are listed in table XII. Also included from the same reference are the CM weight at main parachute deployment and at splashdown. The reentry state vector is presented in table XIII, and the reentry corridor in figure 9.

The aerodynamic coefficients as a function of Mach number and angle of attack, which were used in the six-degrees-of-freedom trajectory simulation are from reference 9. These aerodynamic coefficients along with the corresponding coefficients of lift and drag for the three-degrees-of-freedom simulations were used to determine the CM maneuver footprint. Table XIV lists trim angles of attack, coefficients of lift and drag, and L/D as a function of Mach number.

Aerodynamics for the drogue and main parachute phase simulations consisted of drag values as a function of time from the initiation of the sequence. Drag values for parachutes are given in reference 9.

The atmospheric model used for the simulations was the 1962 U.S. Standard Atmosphere (ref. 10).

Figure 10 shows a plot of the CM maneuver footprint and the nominal ground trace on a map of the reentry area. The nominal touchdown target is 1350-n. mi. down range from the reentry interface. The coordinates of the target are 165° W longitude and 4.3° N geodetic latitude. The simulation uses the reentry guidance as defined in reference 11. Subsequent revisions to the guidance are explained in reference 12.

At the nominal reentry interface, $171^h5^m31.7^s$ g.e.t., the CM is at an altitude of 400 050 ft and the coordinates are 174.75° E longitude and 14.629° N geodetic latitude. Inertial velocity, flight-path angle, and azimuth at this point are 36 000 fps, -6.26°, and 112.595°, respectively.

The nominal mission time from lift-off to drogue deployment, at an altitude of 23 300 ft, is $171^h13^m55^s$. Figure 11, which shows altitude as a function of range to the target, denotes the guidance phases. The load factor at the c.g. reaches a first maximum of 5.46g, $171^h6^m57^s$ g.e.t., and a second maximum of 5.96g, $171^h11^m19^s$ g.e.t.

Time histories of the bank angle commanded by the guidance system, load factor, and altitude are presented in figure 12. The RCS system uses 12.11 lb of propellant for the separation and attitude hold maneuver prior to 0.05g. The RCS system then uses 19.5 lb of propellant performing the guidance commands during the remainder of the reentry. Figure 13 shows a time history of the RCS fuel consumption from 0.05g.

Figure 14 shows the time histories of the total heating rate and the total heat load. Time histories of velocity and flight-path angle, both inertial and relative, are presented in figure 15. The aerodynamic heating during reentry is an arithmetic sum of convective and radiative heating. The convective heating rate and the radiative heating rate

were determined as defined in references 13 and 14. The maximum total heating rate is 287.0 (B.t.u./ft²)/sec at $171^{h}6^{m}42^{s}$ g.e.t., and the total heat is 27 569 B.t.u./ft². In figure 16, the altitude is plotted as a function of relative velocity, and the boundaries for S-band and C-band communication blackout are shown (ref. 15). Figure 17 shows the time histories of the primary DSKY displays, commanded bank angle, altitude rate, and inertial velocity. Table XV gives a sequence of pertinent events, including the periods of communication blackout, which occur along the trajectory.

The drogue chute deployment sequence starts at an altitude of 23 300 ft, $171^h13^m55^s$ g.e.t. Two seconds later, the two drogue parachutes are deployed. At an altitude of 10 500 ft, $171^h14^m48^s$ g.e.t, the low altitude baroswitch closes, and the drogue parachutes are disconnected. One second after the baroswitch closes, the three main parachutes are deployed. The CM, suspended on the main parachutes, reaches splashdown $171^h19^m18^s$ g.e.t. The relative velocity and relative flight-path angle versus time are plotted in figure 18 from drogue chute deployment. Figure 19 shows load factor and altitude versus time from drogue chute deployment.

An EMS scroll (nonexit pattern) is presented in figure 20(a) with the reference trajectory (from 0.05g) imposed upon it. The nonexit EMS pattern has limit lines which will prevent the spacecraft from exiting atmosphere (g < 0.2); therefore, when a tangency occurs in an offset or skip line, the spacecraft is in danger of skipping out of the atmosphere and a crew take-over is required. Another pattern will be available for the lunar mission which will allow the spacecraft to skip out of the atmosphere but not exceed a range of 3500 n. mi.

The commanded bank angle and EMS range-to-go versus the inertial velocity are plotted in figure 20(b).

6.0 TRACKING SHIP POSITIONS AND COVERAGE

The EPO insertion ship is located at a latitude 25° N and at a longitude 49° W. This location provides a minimum of 3-1/2 minutes of coverage after EPO insertion over the entire 36° azimuth spread for a minimum LOS elevation angle of 0° . It is understood that this minimum angle (0° for LOS) satisfies the ship requirement. Figure 21(a) shows the coverage provided. Note that the location is biased because of the better coverage provided by Antigua toward the latter part of the window.

Figure 21(b) shows the coverage for a minimum elevation angle at LOS of 5° .

Figure 21(c) shows the elevation angle at earth orbit insertion for the launch azimuth range.

The general guidelines used in establishing the TLI ship positions are as follows:

- l. Coverage is optimized for the final 2 minutes of the S-IVB preignition sequence.
- 2. The ships are positioned to cover the opening of the window whenever possible and coverage is continuous across the maximum possible launch azimuth range.
 - 3. The coverage is maximized for the first injection opportunity.
- 4. The assumed cruising speed of the ships is 12 knots for repositioning on a day-to-day or month-to-month basis.
 - 5. Coverage is based on a minimum elevation angle of 0° .
- 6. There was an attempt to provide coverage for the complete 36° launch azimuth range unless the window is restricted by the daylight launch constraint.

The positions of the two injection ships and the coverage which is provided are shown in table VIII(a) and (b). The coverage data are shown on bar graphs in terms of the launch azimuths for each launch date. Coverage for the first and second injection opportunities is given and the launch azimuth coverage common to both injection opportunities is identified. Coverage data and the duration of the launch window with the corresponding ship positions for each launch date are tabulated below the bar graphs.

The ship positions and the coverage provided for the December window are presented in table VIII(a). The TLI positions range from about 15° N latitude on December 20 to about 30° S latitude on December 27. A map showing the December TLI positions and the locations of the ships on each day is presented in figure 21(d).

The coverage available from the two ships is generally good for the first 3 days of the opportunity but begins to decrease thereafter due to the ship movement limitations. The island of New Guinea limits the movement of the westernmost ship and is the primary cause of the continually decreasing coverage that begins on December 24. The land mass of Australia prohibits ship placement to cover the opening of the window on the 27.

Some support is provided by the Guam MSFN station on the first 2 days, and the Carnarvon station provides assistance on the last 3 days.

The duration of the launch window for which coverage of the first injection opportunity is provided ranges from almost 4 hours on December 20 to only 10 minutes on December 26.

The ship positions and the coverage provided for the January window are presented in table VIII(b). The TLI maneuvers range from about 5° N latitude on January 18 to near 30° S latitude on January 2^{\downarrow} . A map showing the January TLI positions and the locations of the ships on each day is presented in figure 21(e).

The coverage available from the ships is good for the first day of the January window. The land mass of New Guinea restricts the movement of the ships beginning the second day. Consequently, the coverage available on the second and third days is reduced and launch window coverage is increased on subsequent days. The opening of the window is covered every day except January 23 when the land mass of Australia makes coverage of the opening impossible. Carnarvon station provides all or part of the coverage on the last 3 days of the window. The duration of the launch window for which coverage of the first injection opportunity is provided ranges from about 3-1/2 hours on January 18 to 10 minutes on January 22.

On days when it is practical, the entry ship will be initially placed to assist A/RIA in monitoring the TLI burn. After TLI the ship will cruise to the preplanned entry position. The entry ship positions are not yet available.

TABLE I .- LAUNCH WINDOW CONFIGURATION

 $^{\rm a}{\rm Opening}$ of window is for a 72° launch azimuth, closing for $108^{\rm o}$ launch azimuth.

TABLE II.- LUNAR TARGET SITE POSITIONS

Lunar target site no.	Selenographic latitude, deg	Selenographic longitude, deg	Altitude, n. mi. ^a
I-P-1	-1.2517	43.3014	-1.42
b _{II-P-2}	2.6317	34.0253	-0.82
b _{II-P-6}	0.7322	23.6475	-1.66
b _{II-P-8}	0.3742	-1.3450	-0.50
b _{II-P-11}	0.3255	-19.9003	-0.85
III-P - 9	- 3.0719	- 23 . 5558	-1.21
b _{II-P-13}	1.7667	-41.9389	-1.32

 $^{^{\}mathrm{a}}\mathrm{Assumed}$ mean lunar radius of 938.5 n. mi.

^bPrimary Apollo landing sites.

TABLE III.- SEQUENCE OF MAJOR EVENTS

[Launch occurs at $7^h50^m59.7^s$ e.s.t. on a 72^o launch azimuth]

Mission phase	G.e.t., hr:min:sec	Data summary
Earth orbit insertion	0:11:19.7	Latitude, deg N · · · 32.7 Longitude, deg W · · · -54.7 Inclination, deg · · · 32.6
Translunar injection	a _{2:50:31.2} {	Burn time, sec · · · 311.5 Plane change, deg · · 2.6
Free-return, circumlunar pericynthion	69:09:29.4	Altitude, n. mi 60.2 Selenographic latitude, deg9.1 Longitude, deg174.8
Free-return entry	136:25:18.2	Altitude, n. mi 65.8 Longitude, deg
Lunar orbit insertion	69:07:29.2	Mass at ignition, lb . 62 629.9 Burn time, sec 245.8 Plane change, deg 2.4 Propellant used, lb . 16 044.7
Circularization burn	^a 73:30:52.8	Mass at ignition, lb. 45 565.2 Burn time, sec 9.7 Propellant used, lb. 633.8
Pass over target site (7th rev.)	82:08:26.0	Sun elevation at site, deg 6.6
Transearth injection	89:04:01.8	Mass at ignition 45 666.4 Burn time, sec 171.3 Plane change, deg 0.2 Propellant used, lb . 11 180.4

^aIgnition time

TABLE III.- SEQUENCE OF MAJOR EVENTS - Concluded

[Launch occurs at $7^{h}50^{m}59.7^{s}$ e.s.t. on a 72° launch azimuth]

Mission phase	G.e.t., hr:min:sec	Data summary
Entry interface	171:05:31.7	Velocity, fps 36 070.9 Flight-path angle, deg6.26 Latitude, deg 14.6 Longitude, deg 174.7
Splashdown	171:19:18.3	Latitude, deg 4.28 Longitude, deg164.98

TABLE IV .- SPACECRAFT WEIGHT SUMMARY AND

ENGINE CHARACTERISTICS

(a) Vehicle weights

CM inert, lb			
SM inert, 1b			
SPS unusable, lb 666			
Total inert, lb	23 733		
LTAB, lb	19 900		
SPS deliverable (usable), lb	39 917		
SLA, 1b	4 150		
Injected Saturn payload, lb	87 700		
(b) Engine performance data			
SPS engine 108 thrust, lbf	20 500		
Nominal I _{SP} , lbf-sec/lbm	314.1		
Minimum I _{SP} , lbf-sec/lbm	313.6		

TABLE V .- ASSUMED MISSION

INDEPENDENT EXPENDABLES

 $^{^{\}rm a}{\rm Includes}$ 178 fps for GNCS failure and return from any lunar orbit.

TABLE VI.- MISSION RADAR TIMELINE^a

(a) Definitions of radar table headings

MLA	CB	Merritt Island C-band
PAT	СВ	Patrick C-band
KEN	СВ	Cape Kennedy C-band
GBI	СВ	Grand Bahama Island C-band
GTI	СВ	Grand Turk Island C-band
BDA	СВ	Bermuda C-band
ANT	СВ	Antigua C-band
CYI	СВ	Grand Canary C-band
ASC	СВ	Ascension Island C-band
PRE	СВ	Pretoria C-band
CAR	СВ	Carnarvon C-band
HAW	СВ	Hawaii C-band
CAL	СВ	Pt. Arguello C-band
WHS	СВ	White Sands C-band
EGL	СВ	Eglin C-band

 $^{^{\}rm a}$ The enclosed radar table gives data for the coast phases only. If a station does not acquire or terminate at the nominal minimum elevation of $0^{\rm o}$ or $5^{\rm o}$, the user must then investigate to see if the event took place because of exceeding maximum range, occulation, or end of a phase. All numbers are rounded off to the nearest unit of time, degrees, or nautical miles.

bTime is g.e.t. and range is slant range from the station to the spacecraft (n. mi.). See figure A-3b in the appendix for definitions of RA and DEC, figure A-3a for AZ and ELV, and figures A-3c and A-3d for X and Y. RA is equivalent to -HA in figure A-3b.

TABLE VI.- MISSION RADAR TIMELINE^a - Continued

(a) Definitions of radar table headings b - Continued

TAN TM	Tananarive telemetry
KNO TM	Kano telemetry
MLA SB	Merritt Island S-band
GBI SB	Grand Bahama Island S-band
BDA SB	Bermuda S-band
ANT SB	Antigua S-band
CYI SB	Grand Canary S-band
ASC SB	Ascension S-band
CAR SB	Carnarvon S-band
GUM SB	Guam S-band
HAW SB	Hawaii S-band
GYM SB	Guaymas S-band
TEX SB	Corpus S-band
MAD DS	Madrid deep space
CNB DS	Canberra deep space
GLD DS	Goldstone deep space

 $^{^{\}rm a}$ The enclosed radar table gives data for the coast phases only. If a station does not acquire or terminate at the nominal minimum elevation of $0^{\rm o}$ or $5^{\rm o}$, the user must then investigate to see if the event took place because of exceeding maximum range, occulation, or end of a phase. All numbers are rounded off to the nearest unit of time, degrees, or nautical miles.

bTime is g.e.t. and range is slant range from the station to the spacecraft (n. mi.). See figure A-3b in the appendix for definitions of RA and DEC, figure A-3a for AZ and ELV, and figures A-3c and A-3d for X and Y. RA is equivalent to -HA in figure A-3b.

TABLE VI.- MISSION RADAR TIMELINE^a - Continued

(a) Definitions of radar table headings b - Concluded

SHIP 1 Insertion ship

SHIP 2 Injection ship (1)

SHIP 3 Injection ship (2)

 $^{^{\}rm a}$ The enclosed radar table gives data for the coast phases only. If a station does not acquire or terminate at the nominal minimum elevation of $0^{\rm o}$ or $5^{\rm o}$, the user must then investigate to see if the event took place because of exceeding maximum range, occulation, or end of a phase. All numbers are rounded off to the nearest unit of time, degrees, or nautical miles.

^bTime is g.e.t. and range is slant range from the station to the spacecraft (n. mi.). See figure A-3b in the appendix for definitions of RA and DEC, figure A-3a for AZ and ELV, and figures A-3c and A-3d for X and Y. RA is equivalent to -HA in figure A-3b.

TABLE VI.- MISSION RADAR TIMELINE - Continued (b) 0° minimum elevation

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TABLE VI.- MISSION RADAR TIMELINE - Continued
(b) 0° minimum elevation - Continued

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RADAR TABL	9	S NI	•	'n	'n	v	•	•	•	•	•		-	-	7	8 2	•	82	•	57	*	*			35	35	3.5		
I RAD	TRACKING TIME	NIN SER	٥	0	0	0	0	0	0	0	Э		٥	0	7	13	13	8	12	10	7	~			7	2 10	7 0 7	2 0 8	
VEHICLE			SHIP 1	CY1 CB	CY1 58	KNO TH	PRE CB	TAN TH	CAR SB	CAR CB	SH1P 2		HAW CB	HAW SB	CAL CB	50 019	GYM SB	#HS C8	TEX SB	MLA SB	MLA CB	PAT CB			681 CB	GB1 CB			681 CB 681 SB 671 CB 80 A SB

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TABLE VI.- MISSION RADAR TIMELINE - Continued
(b) 0° minimum elevation - Continued

VEHICLE	æ (ADAR	RADAR TABLE						2	9	1						Ñ	. 110	- X	NOTION TERMINATION		PATA			
	X 04 0	9 Z 2 - - I	STANK LINE LINE TO THE STANK AND THE STANK A	\$	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	2 1	5 F C	* *	95.0	¥2	. >	×	-	S	¥ Q	200	2	SEC	Q ∀	DEC		×	>	RANGE	
ANT SB		96			T.			169	5.5				27	2906			7,			•		0 0	- 83	78699	
1 41HS	7	33	٣	0	~	·O	53	-178		•71	0	06.	1 9	3242	9	ú	3	9.5	-33	•	-97	0 6 0	-83	78699	_
CY1 SB	•	•	21	0	r	13	60	-145	15	•73	0	064	17	4613	0	٥	•	29	-33	9	-61	0 40	- 63	78699	•
MAD DS	ī.	a	4.7	0	m	5	4 2	-129	•	0.8	• -	- 06-	08-	5350	0	00	5	5.8	-33	•	- 64-	0.60	- 83	78699	•
ASC CB	2	12	*	0	e	20	1	-126	35	5.5	-	06-	35	6241	0	'n	32	=	-33	•	- 47	0 40	-83	78699	•
ASC SB	ın	5	φ.	0	•	20	œ	-126	35	155	•	06-	35	6246	0	۰	1,	•	-33	•	-97	0 4 0	-83	78699	•
HAW SB	12	0	35	0	,	- 8	2.1	-37	٥	9.0	0	06	0	36917	0	6 1	8 2	5 6	-31	•	-97	0 0	-1	89758	60
CNB DS	12	52	35	0	Ξ		38	-32	٥	0.6	•	064	06	56219	0	23	23	13	-24	•	96-	0	1 80 1	102812	~
GUM SB	=	57	0.1	0	Ξ	24	*	-32	÷	43	0	0.	7	57956	0	23	7	54	-29	5	96-	06 0	4	102812	~
CAR SB	1.2	20	*	O.	13	26	4	-30	~	9.5	0	0.6	-2	66892	-	-	;	53	-28	•	-97	0 90	• 1	109917	
MAD DS	=	*	32	O.	22	0	29	-27	-1	001	0	06	0.0	98205		•	'n	-	-26	- 6-	-102	06 0	-78	130158	3 4
ASC SB	12	G	23	0	22	<u>₹</u>	5.1	-26	†	96	0	9.0	9	98980		0.1	20	13	-26	1 00 1	8.6	04- 0	9	133373	~
CYI SB	=	25	`	0	22	37	53	1 -26		9.8	0	06		100210	-	10	7	6.5	-26	- 8-	-98	06- 0		133373	n
ANT SB	=	37	30	-	-	39	5.5	-25	-1	9.6	o	9.0		109570	-	13	11	~	-25	6	66-	0 - 0	î	140663	•
BDA SB	Ξ	<u>*</u>	5.1	-	7	-	5.6	-25	Ŧ	•	٥	06	6	099011		13	•	4.7	-25	•	66-	06= 0	•	140663	•
681 58	=	23	51	-	~	53	•	-25	•	66	0	90	6	113165	-	+	•	7.4	-25	7- 6-	-100	04- 0		143035	s.
MLA SB	-	20	13	-	•	a	31	-25	9	66	0	90	6.	113715	-	=	7	*	125	- 6.	-100	0 - 0	7	143364	.
TEX SB	=	20	22	-	*	-	73 24	-25	®	66	٥	06	•	116933	-	5	32	9.	-25	- 6-	101-	04+ 0	=	146130	•
GY# SB	Ξ	-	38	-	ú	•	5.6	-24	8	6	0	0.	- 6-	119488	-	16	7	,	-25	7 6	101-	0 +• 0	=	148092	7
50 075	=	•	27	-	S	37	35	-24	•	100	0	90	1 08	120923	-	•	*	~	- 24	1- 01-	-102	0.60	-78	148778	
HAW SB	=	76	4	-	90	21	•	3 -24	•	66	0	0	•	128254	-	6	+	£	- 54	1- 01-	-100	0 - 0	- 10	549551	*
CNB DS	12	£ 3	£.	-	=	12	53	1 -23	•	6	0	0.	81	135583	-	23	3	36	-23	-	101-	0 0	-79	164479	•
GUM SB	=	37	25		12	0	- 24	-23	6	66	0	9.0	- 6-	137546	-	23	2	•	-23	- 6-	101-	0 0	-79	164479	•
CAR SB	12	27	5.0	-	13	1 42	•	23	8	6	0	90	- 6-	141671	~	~	•	95	-23	- 6-	-100	0 - 90	01-	169017	7
MAD DS	01	3	89	-	22	25	2.6	-22	2	103	0	0.6	17 1	161314	~	٠	0	1	-22		+01-	0 40	-76	182598	•

TABLE VI.- MISSION RADAR TIMELINE - Continued
(b) 0° minimum elevation - Continued

	VEHICLE	-	RADAR TABLE	1 × 8	ř																						
12 5 41 1 2 5 41 1 2 5 41 41 41 41 41 41 41		TRA	EK ING	11.	31			ST	A T 10	N ACQU	11511		A T A						٠,	TATI	ON TER	¥ I W	T I ON	DATA			
1		ĭ	NI W) SEC		DAY HR	S		Ē				>.			NGE		R S	Z Z	SEC		EC	YZ E	. .	×		ANGE
1		-			_	-	7	27				6				381	~	10	23	30			100				5209
1		=	. =	82	_	-		89				=				691	~	2	0	77			100				5209
1		-	1 28			~	-	5.5				00				1540	7	13	7 #	ţ			101				0348
51 11 54 61 12 11 11 12 12 12 11 11 24 12 12 12 11 13 12<	BDA SB	-	_	_		~		20				0.2				385	~	:	71	0.9			101				0348
51 7 8 2 1 7 8 2 1 1 7 8 1 1 7 8 1 1 7 8 1 1 9 1 7 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 3 2 1 1 3 4 2 1 4 2 1 4 2 1 4 2 1 4 2 1 4 2 1 4 2 1 4 4 2 1 4 4 4 4 4 4 4 4 4 4 4 4		-	=	.5	•	7	~	10				- -				1025	~	<u>*</u>	22	=			102				7202
1		-	•			~	•	2.1				0.2				1410	7	<u>*</u>	29	4			103				2265
1		-	_	,2	•	7	*	28				0.2				1593	~	2	37	39			103				4314
1 1 2 5 5 1 1 4 5 5 4 4 5 1 1 1 1 1 1 1 1 1	GYM SB	~	•	,5	•	7		22				20				3347	~	9 !	30	5			103				5850
1	910 05	-			, -	8		5.4				03				1361	~	9	+	9			104	0			2149
58	HAW SB	-			.0	~	œ	34				10				1639	~	6	20	9			102				19611
84 4 6 1 1 59			4		_	~	=	<u>.</u>	•			0.2				5384	7	20	\$	57			-75				11923
1 24 47 2 2 13 94 12 2 14 47 2 2 14 14 14 14 14 14 14 14 14 14 14 14 14	GUM SB				_	~		01				10				104	~	20	57	•			1117				64610
Selection and the selection an			7		•	~		‡				10				1928	~	20	2	5			1117				11 949
Sharing Annual A									107 107	GNITIO	Z		7	day 2	1 hr		29 sec										
5 b 1 24 47 2 21 30 16 -21 -11 -86 64 -24 12 200663 2									7 IO	UTOFF			2	day 2	Ŧ		35 sec										
58 1 24 47 2	CAR SB		1 24			7		30								1563	~	22	15	s,					۳ *		1435
58 1 24 43 2 21 31 -22 -11 101 0 -11 201914 2 2 2 2 2 2 2 2 1 -22 -11 101 0 -11 202731 2 2 2 1 -10 -10 -10 -11 202731 2 </th <th>CNB DS</th> <th></th> <th>1 24</th> <th></th> <th>_</th> <th>~</th> <th></th> <th>30</th> <th></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th>843</th> <th>7</th> <th>22</th> <th>5</th> <th>•</th> <th></th> <th></th> <th></th> <th><u></u></th> <th></th> <th>'n</th> <th>3032</th>	CNB DS		1 24		_	~		30								843	7	22	5	•				<u></u>		'n	3032
58 1 2 2 3 3 1 2	6UM S8		1 24		_	7	-	30								414	~	77	S	13							3220
SS 1 2 2 3 1 1 1 2		_		_		7		31				10				162	~	22	\$	37							3220
SB 1 24 40 2 24 40 2 24 40 1 2 2 202494 3 6 7 1 7 83 17 202494 3 1 2 6 1 6 6 202494 3 1 6 6 1 203444 3 6 1 6 6 203484 3 1 6 6 6 203484 3 1 6 6 6 203484 3 1 6 6 6 203484 3 1 6 6 6 203484 3 1 6 6 6 203484 3 1 6 6 6 203484 3 1 6 6 6 6 203484 3 1 6 6 6 6 6 6 6 6 6 6 6 9 9 9 9 9 <	MAD DS	-			_	7		36				90				156	~	77	*	6							3220
58 1 24 38 2 23 38 27 -19 -11 107 7 83 -17 203544 3 1 1 2 6 -18 -11 117 24 84 -25 D5 1 24 38 2 23 38 44 -21 -10 999 6 56 -80 203585 3 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1			1 24		_	7		38								+66	~	-	~	5 9		<u>-</u>					1812
DS 1 24 36 2 23 38 33 -19 -12 916 11 66 62 203281 3 1 3 11 -18 -11 131 24 56 45 43 DS 29 51 2 23 38 44 -21 -10 999 6 56 -80 203585 3 0 8 34 -18 -11 131 24 56 43 SB 0 4 31 2 23 38 55 -21 -11 -102 1 -89 -12 203859 2 23 43 26 -20 -10 -93 18 -72 -3 SB 0 4 31 2 2 33 38 55 -21 -11 -102 1 -89 -12 203859 2 23 43 26 -20 -10 -93 18 -72 -3 SB 0 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5			- 24		_	8		38				07				1544	m		•	s				**			9282
05 0 29 51 2 23 38 44 -21 -10 •99 6 56 -80 203585 3 0 8 34 -18 -11 131 24 56 43 58 58 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5			1 24			7		38								1281	~	-	•	=				5.4			12789
58 1 24 41 2 23 38 44 -21 -11 -85 36 85 4 201911 3 1 3 26 -20 -10 -93 18 -72 -3 58 0 4 31 2 23 38 55 -21 -11 -102 1 -89 -12 203859 2 23 43 26 -20 -10 -93 18 -72 -3		-				7		38				66				585	•	0	•	34							2789
58 0 4 31 2 23 38 55 -21 -11 -102 1 -89 -12 203859 2 23 43 26 -20 -10 -93 18 -72 -3			1 24			7		38								116	•	-	•	7 7			-63				3175
		_	₹	- -		7		38				0.2	Ĩ.			658	~	23	÷	7 9							3175

TABLE VI.- MISSION RADAR TIMELINE - Continued
(b) 0° minimum elevation - Continued

VEHICLE	- «	DAR	RADAR TABLE																							
	TRACKING TIME	9 N I	TIME			S	TAT	STATION ACQUISITION DATA	SION	1 1 0 N	DAT	_					v	TAT	STATION TERMINATION DATA	N E	NO 1 T	- PA	₹			
	R S	HRS HIN	SEC	DAY	8	MIN SEC	SEC	₹	DEC	A 2	EL V	×	>	RANGE	DAY HRS		Z Z	SEC	RA DEC) E C	A Z	ELV	×	-	RANGE	<u>u</u>
							CIRC	CIRCULARIZATION BURN IGNITION CIRCULARIZATION BURN CUTOFF	ZATIO ZATIO	N BUR	E IG	TOF TOF	≅ ⊾		3 day 1 3 day 1	1 hr 1 hr	30 min 31 min		53 sec 3 sec							
ASC SB	-	=	31	~		4,7	52	91-	01-	41	4 7	43	'n	201684	e	7	5	23	-17	0	96	7	36	7	201278	9.
CY 1 SB	-	Ξ	29	•	-	4.7	0,	-18	=	126	32	25	-30	202366	•	7	•	29	-17	-	1.4.1	4	33	-35	501996	•
MAD 05	-	=	30	٣	-	\$	•	8 7 8	=	\$ 4.2	30	3	32	202461	n	8	•	33	• -	=	1 9 1	37	3	51	202296	•
CAR SB	0	£	6.	r	-	4 60	12	-20	<u>.</u>	- 48	^	683	®	203738	m	7	22	3.1	97-	=	1 9 1	37	51	15	202296	•
ANT SB	0	53	2 2	•	~	'n	30	- 18	=	101	0	0	=	203351	e	7	54	15	1.8	=	191	37	5.1	5	202296	9 6
80 A S8	0	7 6	4.2	~	~	32	39	-17	=	102	0	06	-12	203087	m	8	5.0	21		=	191	37	15	5	202296	96
681 58	-	=	15	e	n	₽	Z.	-17	-	* 0	s	8 5	-	204170	•	*	2.5	4	91-	9	13	70	•	-51	203473	73
ANT SB	-	=	90	e	•	\$	5.5	-17	-	601	23	9		203158	e	*	5.7	. R	• -	9	113	70	6	-21	203473	7.3
MLA SB	-	=	4	•	٣	\$ 2	\$	-17	•:	103	•	18	-13	204323	м	*	57	4	-1:	2	113	20	6	-51	203473	7.3
BDA SB	-	=	52	r	•	\$. ?	5.7	-17	-	113	5	7	-22	203611	e	*	57	4	• -	2	124	28	8	•30	203050	20
ASC SB	-	=	25	~	e	4	-		9	6	16	<u>.</u>	-2	201168	m	*	57	53	-17	•	-116	8 7	.3	7	201240	5
CY 1 SB	-	=	20	•	•	4	•	87-	-	156	4	<u>-</u>	-37	201899	•	*	21	6 6	-12	07.	-177	52	-7	• 38	444	7
MAD DS	-	=	*	r	•	4	1.6	- 1.8	=	175	8	15	*	202324	n	*	5.7	09	-17	9	-163	3.0	5	-1	202540	5
TEX SB	0	15	3. ()	•	7	.	58	9 ! -	-	01	0	90	=	203791	m	7	57	ţ,	-17	-	-163	8	2	=	202540	0.
GYM SB	-	=	3.1	~	ß	*	7	- 16	=	102	7	88	-15	204646	e	•	\$	R S	<u> </u>	î	- 10	-	72	-20	203937	37
TEX SB	-	=	30	~	S	3	26	-16	9	109	13	76	1 8	203962	n	•	5	57	-15	î	119	27	5.	-25	203333	33
GB1 5B	-	=	*	e	ď	‡ ‡	28	• : •	?	120	53	57	-26	203072	•	•	\$	7	-15	î	134	42	39	-31	202628	9
MLA SB	-	=	30	~	s	3	29	• 1 •	9	-	27	9	-26	203221	•	•	5	5.8	5	î	134	42	39	-3	202628	9
ANT SB	-	=	32	m	s	1	30	-1-	?	127	3	36	-24	202225	•	•	9 9	~	51-	î	4.00	e e	-	-26	201979	14
BDA SB	-	=	32	m	ú	3	32	- 1 6	-	135	35	*	-35	202764	•	•	\$	*	s i		153	*	52	1	202521	12
ASC SB	-	=	£.	m	s	1 1	₽	-17	•	. 97	75	- 15	-5	201445	•	•	3	=	91-	î	1 9 4	3	-32	-5	202024	5
CYI SB	-	=	35	n	v	*	4.2	-17	=	-159	20	• 17	-37	202119	•	•	\$	11	•1-	•	-137	4.2	•37	-33	202621	121
MAD DS	-	=	35	•	Ŋ	1	4	-17	-	-149	3.4	25	-25	202805	e	•	\$	7	-	0	-132	27	53	-42	203396	9 6
50 019	0	4.7	45	m	•	6 0	•	1.	-	102	0	9.0	78	203688	e	•	5.5	2 4	91-	9	-132	27	53	-42	203396	•
GYM S8	-	=	4	•	1	4 2	31	• 1 5	Ť	=	26	19	-25	203546	9	40	18 18	1.1	7	•	131	3.9	4.3	-3	203052	25
TEX SB		=	5.1	e	7	42	31	-15	•	\$ 2 8	36	41	-30	203026	-	90	3	22	-	•	1 45	4.7	28	-34	202697	26

TABLE VI.- MISSION RADAR TIMELINE - Continued
(b) 0° minimum elevation - Continued

VEHICLE	-	RADAR		TABLE			A																			
	F	TRACKING TIME	9	TIME		-	in	TATIC	STATION ACQUISITION DATA	15106	110N	DAT						.,	STATION	ON TE	TERMINATION		DATA			
	•	HRS HIN		SEC	DAY HR	S	Z	SEC	.Α Α	DEC	4 Z	ELV	×	>	RANGE	DAY	E S	z	SEC	A A	DEC	42 E	ELV	×	æ >	RANGE
640 05			Ξ	4	•	, ^	42	32		-10	116	8	70 35	6	203991	•	•	*	9.	-	•	1 45	41	28 = 3	-34 20	202697
			=	47	n	^	4	9	-15	•	48	4	52	# 10	202474	n	•	4	56	<u> </u>	•	174	*	in.	-35 20	202431
		-	=	4.7	~	,	42	4.2	-19	6	171	63	ú	-26	201985	•	•	\$	29	<u>s</u>	•	-152	;	7	-25 20	202217
HLA SB		-	=	42	•	^	4 2	£	• 1 5	٠	*	4	29	-35	202583	· m	•	4	52	5	6.	-152	-	,- + I •	-25 20	202217
BDA SB		-	Ξ	43	n	1	45	1. 00	•	-10	170	9	•	-45	202506	•	•	5.4	31	-	•	-165	•	,- :1.	-41 20	202685
ASC SB		-	Ξ	*	~	^	45	25	91-	î	9.	4	4.3	7	202553	~	90	3	35	-1	•	-95	30 -	0	-4 20	203529
CY1 58		-	=	3.6	•	^	4 2	æ	9	•	-126	*	.50	-29	203088	m	∞	2	36	41-	- 6	-113	22 +	·- /•	-22 20	203950
MAD DS		-	=	39	•	1	£	o	-16	01-	-122	-	21	-53	203885	~	•	3	3.9	•	7	60t-	•	- 14	-69 20	204734
HAW SB		0	-	7	•	•	25	30	*	٠	6	0	06	ů	205105	•	•	₽	12	-15	•	-109	•		-69 20	204734
HAW SB		-	=	3.1	•	۰	-	5.	*	•	104	Ξ	79	=	204661	m	01	52	76	- 13	•	112	7,		-20 20	203955
		-	=	34	~	•	-	#	-	•	1 43	\$	30	-34	202848	•	9	52	37	7		167	53	•	-36 20	202752
		-	Ξ	34	e	•	.	*	1.	÷		37	9	Ē	203252	r	0	25	3.9	-	6 0	1 6 1	*	*	14 20	203090
1EX 58		-	Ξ	9	٣	•	*	•	• 15	•	162	25	*	-36	202619	ď	01	5.2	?	-		-170	53		-36 20	202738
MLA SB		-	=	37	m	٠	7	=	- 15	•	-171	25	•	-37	202605	•	10	5.2	+1	-	•	9 + 1 -		- 28 -	-34 20	202984
		-	=	36	٣	٠	£.	13	5	•	-166	4	0	*35	202553	•	0	25	*	-	•	. 4.1	+7 -	- 06-	-32 20	202979
ANT SB			=	39	٣	•	=	.	• 15	•	-134	4	-27	-24	202528	•	-	52	5.2		7	-118	; ;	4 5 + 1	-21 20	203235
		-	=	0,7	٣	•	∓	<u>*</u>	• 15	î	-149	7	• 28	-38	202941	c	9	52	5.3	-	•	-131	35 .	1 0 7	-32 20	203542
ASC SB			=	36	m	۰	7	2	91-	•	96	8	-72	•	204251	~	0	52	25	- 15	•	96-	-	6	-B 20	205432
CY1 SB		0	5	26	e	٠	Ŧ	71	• ! -	•	-107	7	-78	9	204596	n	0	•	41	97-	•	# 9 B	-	•	-8 20	208432
HAW SB		-	Ξ	‡	n	=	39	•	-13	•	=	36	20	-23	203585	•	12	8	20	-12	•	134	•	32 -	-27 20	203169
67 H SB		-	=	38	n	=	39	24	-	Ť	-173	53	ů	136	202846	~	12	5	~	-	•	-147	•	- 38-	-34 20	203207
910 02		-	=	36	m	=	39	25	‡ 	î	177	*	*	7	203123	•	12	5	-	-13	7	-147	•	- 97-	-34 20	203207
TEX SB		-	=	3.6	m	=	39	77		•	-152	50	•25	-35	502969	~	12	3	*	-13	7	-131	; ;		-30 20	203531
681 58		-	=	38	m	=	39	31	† 1		-129	*	4.	-29	203402	•	12	5	•	-13	7	-115	27 •	- 19.	-22 20	204219
MLA SB		-	=	36	n	Ξ	39	32	1		-132	\$	7	-	203380	6	12	3	90	-13	9	8 ! ! 8	28	69-	-24 20	204160

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TABLE VI.- MISSION RADAR TIMELINE - Continued
(b) 0° minimum elevation - Continued

VEHICLE	5. A.	DAR	RADAR TABLE																					
	TRACK ING	9	TIME			w	STATION		1510	ACQUISITION	DATA						STA	1 1 0 N	TERM	INAT	STATION TERMINATION DATA			
	HRS MIN	z T	5 £C	DAY HRS	S E	MIN SEC	SEC	K	DEC	AZ E	ELV	×	æ ⊁	RANGE	DAY	Z S	HIN SEC		RA DEC		AZ ELV	×	-	RANGE
ANT SB	-	=	34	~	=	39	35	-15		===		-57 -18		203823	~	12	51	ī	* -	-8 -103	3 16	+ 7 4	-13	204857
BDA SB	-	Ξ	3.4	۳	=	39	36	# 	•	-121	27 =	- 60 -2	-27 20	204049	~	7	5.1	ĩ		401- 8-	-	• 75	-	204954
	-	5	ū	e	=	45	32	-13	•	6	0	0.	07 10	205288	r	12	50	37 -	*-	-8 -109	*	-75	9	204956
GUM SB	0	5	57	•	1 2	3.4	£	-12	•	9 6	0		-8 20	504899	n	12	0.6	- -	+ -	-8 -109	**	•75	9	204956
	-	Ξ	36	r		37	8	-12		83	22 -	8 -	67 20	204617	~	*	6 0	54	-	-6	71 35	-26	5	204071
		=	31	м		37	25	-12	P	102	15	75 -	-11 20	204991	•	*	40 40	- 95	=	-7 107	12 31	\$	*	204254
	-	=	,	•	- 3	37	35	-13	4	150	9 9	î •	-29 20	203034	•	<u>*</u>	- •	- 91	-15 -	-7 -178	1 8	7	-29	203067
6LD 05	-	=	3. 2	n	2	37	Ŧ	-13	80	7 7 1 1	5	Ŧ	-27 20	203677	~	-	6	30	- 17	-7 -127	27 30	*	1 1	204328
GYM SB	-	=	1	n		37	4	-13	0	-133	12	- 39 -	-31 20	203584	~	Ŧ	٠٠ ج	30	-15	-7 -118	9 30	-57	-24	204355
TEX SB		=	47	e	13	37	4	-13	80	-121	32 -	¥ 5 =	-26 20	204027	~	*	•	34	. :-	-7 -109	61 60	•10	9	204944
MLA SB		=	4.7	•	13	37	4	-	6	-110	6	- 0/-	-19 20	204765	~	*	0.	35 -		-7 -101	•		=	205793
681 88		=	47	•		37	1	Ŧ 	•	-108	17 -	-72 -	-18 20	204847	~	*	•	35 -		-7 -101	* 10	1 B 5	=	205793
BDA SB	0	2.1	32	e	2	37	50	1 2		-102	.	1 98 •	-12 20	205607	m	13	20	- 12	. :-	-7 -101	*	182	=	205793
	0	- 6	99	٦	1	37	50	-	9	664	3	38.5	-9 20	205592	~	13	23	9		-7 -101	* 10	60.5	=	205793
	0	26	ar ar	~	*	2.1	53	=	-1	41	0	06	-7 20	204764	m	<u>*</u>	•	0 37	-13	-7 -101	* 10	- 6	=	205793
CAR SB	-	=	33	e	5	35	32	-11	7	9.0	9	4 7	0 20	205201	•	9 1	4	, ,	01-	•	81 32	60	7	204513
CNB 05	-	=	3.4	r	5	35	37	-	•	0.9	‡	-27	39 20	203802	m	9 -	<u>*</u>	-	=	•	40 S4	-29	22	203546
85 HUS	-	=	33	m	-	35	1	=	-		4	4	-17 20	203866	•	9 1	4.7	- 11	01-	-1 -1-	126 57	78	=	203449
HAW SB		=	30	٣	5	36	0	-12	-	-155	80	57.	-29 20	203248	•	9 1	4.3	- 16	=======================================	-7 -131	31 49	-33	-26	203753
640 05	-	=	27	n	15	36	-	-13	-	-1117	22	6	-55 20	158402	•	9	4.1	. 76	-15	-7 -106	01 90	28	-72	205764
	0	*	33	•	15	36	-	-13	•	-103	•	- 18-	-13 20	205605	m	91	50	7 7	-12	-7 -106	01 90	88	-72	205764
GYM SB	-	=	36	•		36	1.2	-13		-110	20	- 69.	-19 20	204952	•	•	4.7	37 -	-12	-7 -101	10	=	=	205969
							F	TEI IGNITION	TION			3 day	3 day 17 hr	4 min 2 sec	ပ္က									
							F	TEI CUTOFF	JFF.			3 day	17 hr	6 min 53	sec									
CAR SB	•	=	52	e	17	21	-	-10	7	11	39	20	10 20	204890	*	~	9	. 65	-13	•	-41	0.0	•	196223
CNB DS	7	7	33	•	1.7	21	-	7	•	36	8	-29	13 20	991102	*	0	52	. 15	-12	•	-97	0 0	-1	196223
GUM SB	•	5.7	w	r	17	21	7	=	•	138	63	•	-19 20	204009	*	0	9 7	30	-12	•	- 44	06-0	-	196223

TABLE VI.- MISSION RADAR TIMELINE - Continued
(b) 0° minimum elevation - Continued

VEHICLE	-	RADAR TABLE	1 × E), E																					
) 	TRAC	TRACKING TIME	-	Ä			STA	1 1 0N	STATION ACQUISITION DATA	S1710	¥ O	₹						STAT	NOI	FERMI	STATION TERMINATION DATA	1 DAT			
	Ĭ	N N N N N N N N N N N N N N N N N N N	SEC		DAY HR	Z I E	N SEC		RA DEC	V	ELV.	×	>	RANGE	DAY	2 2 3	Z	SEC	æ ₹	DEC	74	ELV	×	-	39844
					-	_	21	35 • 1	-12 -7	-123	* 2	143	-24	204764	•	20	3	\$	-12	*	-97	0	04-		196223
						7			-12 -7	- 100	m -	76	-19	206912		17	33	₽	-12	- 1	-97	•	0.	.7	196223
	-	·	4 2		3	8	5.2.2	23 - 1	-111 -7	100	0	•	90	200649	7	•	58	us.	=	•	•	0	. 06	- -	187207
ASC SB	~ ~	•	01	•	3	~	'n	ī	-10 -7	6	-	•	-	200402	*	Ξ	un.	24	-12	*	•	0	06-	•	105736
	=	24	- -	.0	3	3	28	35 • [-10 -7		-	•		199953	*	-	53	20	-12	•	•	•	04-	•	185736
	=		. 33		7	7	27	-	-10 -7		٥	9.0	-	164961	*	-	*	33	7	:		0	0		949181
80 A SB	=	-	24		*	7	•		-10 -7	8	-	6		990961	*	<u> </u>	_	5	7	١ - ١	6-	0	0-	•	181627
681 58	=			vo.	•	ω 	38	36	-10 -7		•	•	- 8	195070	*	5		7	=	-1	- 47	0	04-	-	180274
MLA SB	_	1 24	3. C.	ú	.	٠ س	0	+3	-10 -7		0	90	8	10401	#	5	<u>.</u>	- 28			6	0	06-	7	990081
TEX SB	=	1 26		-	+	3*	25	3.0	-10 -7	. 6	6	•		193471	#	9	22	us a.	7		16- 1	0	- 90	-	178476
	=	1 25	. 95	. 40	*	n 4	•	•	-10 -7	8		•	•	192417	*	13	15	90	7	7 -	- 97	0	04-	-1	177174
6LD 05	=		·-	•	*	•	•	21 -	-10 -7	66 4	0	90	. 81	191806	7	- 12	35	37		`- -	86-	0	0	-82	176686
E S E			36	٠	*	۰	~	•	-10 -7	•	0	90		186412	*	20	25	‡		•	16- 1	0	06=		172182
CNB DS	12	2 26	2.4		-	8	0	37	•	•	0	•	9 83	184513	ın	•	27	-	-	S • 0	94- 1	0	0,6	*	990991
S MUS	-	1 42		5.0	*	~	- -	3	9-	-	0 6	6	7- 0	183617	ď	_	23	?	01-	0	96- 9	0	90	*	990991
	-	12 15		-	-	+	28	1.1	î	•	•	•	•	9+1191	ų,		£	3 28	01.	5- 0	- 95	0	- 90	è	162267
MAD DS	-	91	S.	0	*	. 22	4.2	31	9	9		•	0 82	148557	LO.	-	=	= -	9	9 - 8	- 18	0	90	- 8 2	140744
ASC SB	-	. 21	9.	0-	4		=	6.	S -	9 6 9	•	•	•	160111	us.	=	12	œ	•	6	- 95	0	9.0	Ş	146727
CY1 SB	-	1 31	9	0	7	2	32	•	9- 8-	6 97	0 /	•	- 0	167548	ın	-		3 56	•	4 -5	* * 5	٥	-90	'n	146727
ANT SB	-	. 45	2 34	7	ī.	~	32	24		%	9	•	•	162580	un	-	-	4 50	9	8	95	0	- 90	ş.	140543
BDA SB	-	11 28		ú	s.	~	2	24	7	16 9	0 /	•	- 0	162026	un	-	_	09 6	•	1.5	96- 9	0	0	•	140368
681 58	-	11 34		25	ហ	-	£	•	-7 -6	•	7 0	•	- 0	160553	ut	51 .		+ +	•	15	96- 9	0	•	;	138339
HLA SB	-	11 32		38	s	~	\$ S	12	- 1-	•	0	•	- 0	160239	u1	==	5 26	•		5	96- 9	0	90	†	910061
TEX SB	-	11 33		5.7	ហ	uñ.	0	51	-1 -4	26 9	7 0	•	7- 0	158291	wi	<u>~</u>	*	*	7	• •	96- 9	0	-30	•	135573
6YM SB	-	11 34	*	e	ı,	ru	4.		-1 -6	4 47	0 ~	6	0	189951	uı	2 17	7 28	*	t - 1	. ·	S - 3	0	06-	S	133596

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TABLE VI.- MISSION RADAR TIMELINE - Continued (b) 0° minimum elevation - Concluded

VEHICLE	 ax	ADAR	RADAR TABLE																	1					
	TRAC	K I NG	TRACKING TIME				STATION	NOI	ACQUISITION	1110	DATA	<					8 ± 8	STATION TERMINATION DATA	TERR	INAT	Y O NO	⋖			
	H S	HRS MIN	SEC	DAY	DAY HRS	Z	SEC	Α.) DEC	A 2	ELV	×	-	RANGE	DAY HE	E SE	MIN SEC	C RA	A DEC		AZ ELV	*	>	RANGE	
61.0 05	=	76	30	ı,	•	23	38	-7	*	41	0	90	83	155820	us.	17	20	8 -7		-5-	0 96-	9.0	101	132802	
	=			ď		•	~	4	5 -	96	0	90	9	150764	so	20	£9	36	- ′-	7	-95 0	- 0	•	125922	
	12		£		12	- 5	9	•	‡ 1	9.5	0	90	9	144618	•	0	32 2	23 -	9	-2 -93	0	90	-87	116773	
	=	4	33	us.	1.5	4	38	9-	•	9.5	٥	90	3	143472	•	0	38 1	- 01	•	to- to-	•	- 0	7	116525	
	12	•	29	ısı	÷	#	2 45	5		4	0	9.0	7	139574	•	~	52 1	, ,	- 5	-2 -6	-92 (0 0	2	110642	
		37		un.	5 23	-1		*	S	96	0	6	9	120526	•	0.1	-	- 51	- 7	6-	*6-	0 40	98-	87399	
	7		23	un	5 23	28	=======================================	-	3 -3	9.3	O	6	7	119483	•		30 3	33	7	-1 -91		04- 0	ī	84593	
	=	47	4.	LTI	5 23	£.	3 38		¥ 1	45	0	0.6	\$	118836	•		31.	- 52	7-	-2	-93	04- 0	7	84544	
	=	57	1,	•	-	47	7 31	-5	2 -4	4	0	90	Ť	110853	٠	*	*	0	7	ĭ	16-	06- 0	7	73019	
	=	9	4.	7	۰۰ م	_	4 17	-2	2 - 4	9.5	0	9.0	ŝ	110091	•	*	55	-		7	-92	00		72364	
	. =	S		•		57	7 28	-2	1.	4	0	90	Ť	107668	•	1.5	. 63	9.	•	7	16-	06- 0	7	68621	
	=	5.5	1,7	•		_	u1 ap	î G	2 - 4	*	0	6	*	107177	•	9	m	22	•	7	16.	06- 0	ī	91649	
	-			,		<u>-</u> -	7. 2.	1	-3	9	0	•	Ť	103998	•	17	*	91	_	7	-91	06- 0	7	98189	
	12		0.	•	•	-	51		1 -3	•	0	06	ŧ	101372	•	9	=	52	~		06-	0 - 90	0	59077	
50 019	: =	5.		,	•	37	7 48		1 -3	4	0	0	9 8	10001	. •	9	37	\$ *	7		- 6.1	0 6 0	69- 0	57144	
98 AAA	12			,	•	62 (60	1 -3	93	0	•	.3	91249	•	21	£	7	•	7	88	06- 0	7	41787	
	15			-	9	<u>د</u> د		7	3	89	0	-90	9	19477	1	-	8	24	9.	1 9 1	-70	0 - 0	00	21368	
SOM SB		3 #5	12 27	-	•	_	17 53		3 -1	6	0	•	7	78354	7	~	•	20 -145		20	7.0	•	90 20	=======================================	
CAR SB	-	1 20	42	-	-	2	29	8	S	68	•	•	-	70196	,	~	6	44 -145		20	70	•	90 20	•••	
MAD 05		*	÷.		,	7	26 51		52 #	50	0	9 40	99	25674	7	~	=	94 - 145		20	70	•	90 20	1166	
	•	2 10	30		_	7 0	28 20		24 12	S.	₹	4.0	78	23400	^	7	38	50 -145		20	70	•	90 20	••••	_ :
CAR CB	,	2 21	1 12			0	28 3	32 1	16 13	9#•	39	-42	33	23400	7	~	P	45 -145		20	70	•	90 20	• • • • • • • • • • • • • • • • • • • •	_
PRECB		1 47	24		_		36 21		27 13	63	20	9	25	23400	^	~	23	46 -145		20	20	•	90 20	•	_
							Ш	NTRY	ENTRY INTERFACE	RACE		7 day	3	hr 5 min 3	32 sec										

TABLE VI.- MISSION RADAR TIMELINE - Continued (c) 5° minimum elevation

VERICLE .	RADAR TABLE																								
-	TRACKING TIME	197	, I HE			J ,	STATI	4 NO.	CQUIS	1 V 10N	STATION ACQUISITION DATA						N	FATIL	NO TE	N I N	STATION TERMINATION DATA	DATA			
	N S R I		SEC	DAY	H S	I	SEC	æ	DEC	7 Y	ELV	×	E	RANGE	DAY	2 2 3	Z	SEC	8 .	DEC	AZ E	ELV	×	<u>-</u>	RANGE
•	a		•	0	0	=	20	•	•	9	7	83	ū	541	0	0	=	35	150	1	9	ı	9	w	104
80 Y CB		0	. •	0	0	=	, 50	-52	•	60	7	83	ū	541	0	0	Ξ	35	-50	7	8 5	ın	S	: IA	104
- L	0	~	Ŧ Ŧ	0	D	=	20	119	S	-30	•	• 78	5	555	0	0	₹.	*	=======================================	9	39	•	7	ī	70
CY1 SB	0	*	92	0	0	17	32	178	11	+73	S	5 8 2	9.1	599	0	0	22	30	-	∞	113	s.	5	-23	544
80 LX	0	*	8	0	0	17	32	178	11	-73	un.	58	9 7	599	0	0	22	30	7	8	113	ø	5	-23	245
KNO T	0	7	30	٥	0	24	47	-160	ŝ	-36	'n	• 8 Z	# S	290	0	0	29	11	22	•	41	ı	5 8	-1	284
TAN TH	0	8	22	0	0	38	3.4	01-	9	*		P	83	578	0	0	7	99	2.	53	63	•	-	12	579
CAR SB	0	~	53	0	0	53	39	-61	7	7	ı,	-82 -	-51	587	0	0	5	32	147	-52	146	un.		49-	297
CAR CB	0	~	53	0	O	5.3	39	- 9	1 0	-141	ru I	-82 -	-51	587	a	0	Q	32	167	-52	4 4 6	N.	=	-54	201
	0	~	7.	0		0	4. 00	•	6.7	-62	ru.	- 64-	-62	5.04	0	-	*	12	125	45	26	•	*	97	2 8 2
	٥	7	55	0	-	29	1.7	125	-24	-121	r.	1 # 8 -	-31	765	0	-	*	=	-73	13	7.8	ø	9	71	2 4 4
	0	*	52	0	-	30	5.0	1 4 3	1 -34	-136	'n	-83 -	1 4 6	593	0	-	35	5	-78	7	8	•	85	:	244
	•	*	25	0	-	32	Ξ	123	7	-91	'n	8 8 5	7	597	0	-	37	٣	-5	27	62	s	4	28	004
EGL CB	0	*	25	0		34	37	134	•	- 90	'n	1 09 5	0	665	0	-	39	53	1 4 70	1.1	7.	w	8	<u>.</u>	† 05
HLA SB	0	*	36		-	36	7	132	19	-71	5	58	6	009	٥	-	7	43	-33	27	62	'n	.	97	109
	0	*	35	0	-	36	60	131	6.1	•71	'n	5 8 4	6.	009	0	-	\$	43	-33	23	29	un.	*	9.8	104
KEN CB	0	*	36	0	-	36	•	132	61 2	-71	'n	4 8 5	6.	009	O	-	40	45	-33	27	62	us	*	8	109
PAT CB	0	*	32	0		36	=	131	1 21	+69	'n	- 85	21	009	٥	-	\$	45	-33	27	62	ø	*	:	10
681 CB	0	~	09	0		36	57	127	7 33	-56	ū	*	3.4	009	o	-	\$	57	-25	38	20	G	83	₽	
6B SB	0	~	0,	0	-	36	57	127	33	156	s	7 ED	£	009	Э	-	\$	57	-24	3.8	20	us	3	40	109
1 41HS	0	*	1.9	0	-	4,	*	153	3 42	**	Ŋ	• 8 3	*	009	0		41	5.6	-	11	*	un.	8 2	9	247
CYI CB	٥	-	39	•	-	5	5	-129	9 -32	-130	ď	-83	0 7 0	245	0	-	53	30	-63	42.	1169	ú	9	-78	240
CYI SB	0	-	39	0	-	5.1	5	-128	8 -32	-130		- 684	0+-	245	a	-	53	30	-83	-56	-169	úA	19	-78	240
KNO TH	0	~	27	0	-	5.0	36	-118	6 -23	-115	S	- 65	-24	10 10 1	0	~	-	7	-54	-72	-175	'n	#	4 P	3
1AN 13	0	*	9	0	7	01	0 - 0	-79	80	• 1 4	'n	5 60 8	=	580	0	8	*	05	104	Ŧ	132	ıA	2	-42	100

TABLE VI.- MISSION RADAR TIMELINE - Continued (c) 5° minimum elevation - Continued

Name Name	VEHICLE	I RADAR TABLE	DAR	TABLE																				
1		TRACK	9 N E	TIME				STAT	NOI.	10901	1110N	DATA				~•	STATI	NO NO	Z Z	NO I I	DATA			
1 1 1 1 1 1 1 1 1 1		H S	ž	SEC	DAY		ĭ						RANGE	DAY			SEC) 3 0		2	×		RANGE
1	AR SB	0	~	45	0		26				-141		586	0	7	30	1.7	173	-29	120			30	9 6 9
1	CAR CB	0	•	45	0		7.7				-142		586	0	~	30	1.7	173	-29	120			0	:
12 12 12 12 13 14 14 15 15 14 15 15 15	SHIP 2	0	1	7	9				e C	99- 9		5 -7 0 da	3.	32 sec	~	4	35	•128	-	60	un .	3.0	-	585
2 3 4 5 6 5 6 7 7 7 7 7 7 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9								= =		OFF		o da		32										
51 41 42 6 6 40 11 6 6 7 11 11 6 12 42 6 6 6 6 7 11 6 12 42 12 42 12 42 12 42 12 42 12 12 12 12 42 2 6 12 42 6 12 42 6 12 12 42 6 12 12 42 6 12 13 14 6 12 13 14 14 15 14 15 14 15 14 15 14 15 14 15 15 14 15 14 15 14 15 14 15 14 15 14 14	AL CB	7	23		0	~	57			-23			1105	0	'n	20	51	1.5	~	60				23400
11 42 12 6 13 6 13 6 13 6 13	50 01	13	-	55	0	7	5.7				-120		1 8 1	0	1 5	5	32	-33		101				74778
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TABLE VI.- MISSION RADAR TIMELINE - Continued
(c) 5° minimum elevation - Continued

	<u>.</u>	N A	RADAR TABLE																						
	TRACKING	9 N I 3	TIME			S	TATIO	STATION ACQUISITION	9 U I S I	4 1 ON	DAT	<					S	7 A T 31	NO TE	N II N	S _t ation termination data	DATA			
	H &	HRS HIN	SEC	DAY	I S	Z Z	SEC	A A	DEC) Z Y	ELV	×	>	RANGE	VA0	H & S	Z II	SEC	R A	DEC	42 E	ELV	×	>	RANGE
S MUS	-	*	'n	0	Ξ	4	•	-31	-	4	ú	9	7	59313	0	23	0	*	-29	5	193	ū	29 -	7 7 7 7	101172
	7	34	41	0	2	4.0	22	-30	-2	0.6	s	8 5	0	68157	-	-	7 4	0	-29	•	46-	'n	- 85	7	984801
MAD DS	10	•	38	0	22	28	e e	-26	-	¥0.1	'n	7.0	7.5	99390	-	60	37	41	-26	ô	-106	ū	7.3	-73	128678
ASC SB	=	5.4	01	٥	22	35	25	-26	ø	9.5	ď	5	ů.	99781	-	•	59	35	*2*	8	-97	r.	£ 65		132199
CY1 SB	0.1	3.8	56	0	23	-	21	-26	-1	101	'n	.		101153	-	0	30	4	-26	9	-41	s	- 85	-7	132199
ANT SB	0	₹.	1 2	-	7	-	7.6	-25	-1	66	s	8	•	110335	-	12	5.5	37	-25	6	101-	'n	-85 -	=======================================	139498
BDA SB	0 1	25	.s.		7	26	33	•25	80	103	'n	\$	-13	111569	-	12	55	23	-25	6	-101	s,	- 85	=======================================	139498
681 58	01	37	5 -	-	М	91	4	-25	œ 1	101	s	9.2	=======================================	113982	-	13	53	52	-25	•	-103	ı.	- 92	-13	141820
MLA SB	0.1	33	5!	-	•	28	'n	-25	œ •	102	ß	85	-12	114548	-	-		20	-25	6	-103	'n	- 95	-13	142135
TEX SB	-	4.	1.2	-	7	35	•	-24	φ.	102	s	85	-12	117732	-	2	۰	28	-25	6	-103	S	- 88	- 13	144823
GYM SB	0	32	57	-	Ŋ	29	3	-24	60	102	ß	9	-15	120270	-	16	7	20	-25	6	-103	'n	185	-13	968941
90 079	0.	5	36	-	9	~	•	-24		101	S	7.0	75	121791	-	9	8	43	-25	-10	-105	'n	72 -	-74	147507
HAW SB	01	45	52	-	60	43	21	-24	60	101	'n	8	=	128921	-	61	52	4	-24	0.7	-102	\$	- 85	-12	154533
CN8 DS	=	53	£.		Ξ	37	4.2	-23	-1	95	S	4	83	136312	_	23	31	70	-23	î	- 9.7	ú	5	7	163307
85 MU9	0.1	55	0.5	-	12	7 7	25	-23	6	001	ď	8 5	01-	138108	-	23	1.7	9.	-23	6	- 9.7	w	5.		163307
CAR SB	=	4.3	0		<u>.</u>	7	54	-23	æ •	96	v	85	9	142260	7	-	4 7	54	-23	•	86	'n	- 85	a	167959
ASC SB	Ξ	7	51	-	22	₹	20	-21	6	66	'n	8	6	161802	7	10	12	35	-22	0.	66-	'n	- 8 5	<u>.</u>	184212
HAD DS	•	*	5.0	-	22	53	31	-22	01-	108	'n	7.4	7.1	161980	7	00	*	77	-22	-	66-		9 2	6	184212
CY1 SB	0.	52	89	-	23	22	12	-21	01-	104	S	8	= -	162983	7	0-	*	30	-22	07-	- 89	'n	- 8 5	•	184212
ANT SB	01	4	22	~	8	17	13	-21	-10	102	'n	9	-15	168960	7	:	•	36	-22	=	-103	'n	- 95		189448
BDA SB	0.1	-	43	7	7	S	34	-21	0:-	106	ហ	9 2	-15	906691	7	12	57	91	-22	=	-103	'n	• 85	2	189448
681 58	9	52	£.		•	33	8.	-21	01-	104	S	85	7	171489	8	-	99	25	-22	=	-105	ú	- 5	5 -	191047
MLA SB	01	21	52	7	•	4. G	6 7	-21	07-	105	s	8	5	171886	8	<u>.</u>	•	T	-22	=	-105	'n	- 85 -	- 15	191318
TEX SB	-	22	₹	~	7	51	33	-21	-10	*0	'n	85	=	174073	7	5	=	7	-22	=	-105	ů,	- 65	51-	193289
GYM SB	01	21	1	7	ú	\$ 2	38	-21	<u>-</u>	501	ú	85	- 15	175800	7	1 6	7	77	-22	=	-105	ıΛ	. 58-	- 15	194903

TABLE VI.- MISSION RADAR TIMELINE - Continued (c) 5° minimum elevation - Continued

VEHICLE	 ar	D.A.R	RADAR TABLE																						
	TRACKING TIME	2	TIME			S	STATION		ACQUISITION		DATA						S	TATIO	STATION TERMINATION	NATIO	Y O N	₹.			
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			, c		4		- 2	-21	=	107	ď	7.3	73 17	176908	8	9 .	21	9	-21 -11	-108	5	7.4	-12	182331	
	2 9	- ;	, ,		, a	2	: :		=	+01	Ŋ	5	-13 18	181863	2	6 1	28	£	-22 -11	-105	٠.	9	*	200955	
	2 '	ž !	0, -	• ^	• :	, ,		-2	: :	6				186877	7	20	26	5,1	-21 -11	-1	5 38	-1-	4.49	201923	
	•	<u> </u>	- ·	• ^	: :	.	•	2	: -	102				188400	7	20	57	~	-22 -12	2 -117	7 38	4	-21	501949	
	•	9 '	u (• (•	; '	•							191343	8	20	26	4	-22 -12	2 -117	7 38	4.4	-21	201949	
CAR SB	•	4	30 	•	<u>.</u>	`	ה ה	=	NO!	:	~		21 hr	7 min	29 sec										
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C NB D S		24	. 41	7	2 1	30			=	- 6	31.	• 15	-57 2	201843	7	22	5.5	•	-21 -10	0 -92	2 15	•	-75	203032	
		24	43	2	2.1	30	3.	-22	-12.	-112	30	. 58	-19 2	201914	2	22	5.5	13	-21 -11	1 -105	5 12	-18	-	203220	
				~	22	53	•	-19		1 00	G	5	-10 2	203510	7	22	12 2	37	-21 -11	501- 1	5 12	-78	7	203220	
	,	24		~	23	38	1 9	61-	77-	6	9 !	7.4	-9 2	202994		-	7	5.9	-18 -10		97 36	2.0	7	202181	
		7		7	23	38	27	61-	-11	107	7	. 83	-17 2	203544	e,	-	e	S	-18 -11	1 117	7 24	4,0	-25	202826	42
	-	24		7	23	38	33	-19	-12	116	=	99	62 2	203281		-	٣	=	-18 -11	1 131	1 24	9 2	ţ	202789	•
		.		2	23	38	#	-21	o:	66-	•	95	-80 2	203585	7	23	4 2	\$	-18 -11	1 131	1 24	95	4	202789	
	· -	4		8	23	80	7	-21	-	80 73	36	3.	*	201911	e	-	М	56	-20 -10		-93 18	-72	•	203175	
200	•	•						್	SIZATI	ON BU	RN IG	N	N		3 day	1 hr		30 min	53 sec						
							ਹ	CIRCULARIZATION BURN CUTOFF	RIZATI	ng NC	RN CI	UTOF	ĻL		3 day	l hr	31	min	3 sec						
	•	:	-	•	-	4.7	5.2	97	01	47	4.7	£	.5	201684	·	~	5	23	- 11-	01-	†9 96	¥ 56	7	201278	
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					~	28	-	2 -17	-10	102	'n	85	-15	202699	•	7	5.5	5	-18	=======================================	161	37 51	5		
	, c			eri	~	57	65	9 -17	07-	901	ហ	8	91-	203979	r	8	5	21	- 18 -		161	37 61			
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	- •	. :		e.	•	3		1 - 18	01-	66	76	<u>-</u>	?	201168	~		4 57	53	-17	1 - 6 -	911-	87 -3	7 -	201240	0
	-, -			. "		*	4	. 18	- 10	156	£ 0	6	-37	201899	Η,	•	4 57	50	-17	1- 01-	-111	52 -2	2 -38	1 201944	
26 113	-		; •																((

TABLE VI.- MISSION RADAR TIMELINE - Continued
(c) 5° minimum elevation - Continued

VEHICLE	I RA	DAR	RADAR TABLE	<u></u>	,																		*		
	TRACKING	5 N I	TIME	w			STAI	1 1 0 N	STATION ACQUISITION	SITIC	N DATA	¥.					S	*AT10	N TE	STAION TERMINATION	NO I	DATA			
	S E	HRS MIN	SEC	DAY	H	I	N SEC		RA DEC	7 Y Z	ELV	*	>	RANGE	DAY	S.	Z I	SEC	ĸ	DEC	7 4	ELV	×	>	RANGE
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	-	0	35	г	_	5.7	- 1		-17 -10	105	.0	88	- 15	203625	e	4	2.5	4	-17	===	-163	3.6	3	-13	202540
1EX 58	-	=	30	-	.n	7	t 26	1 6	- 10	104		7.6	1 0	203962	m	•	5	53	91-	6	- 6	23	•	-25 2	201333
GB1 SB	-	Ξ	*	Ε,	'n	7	7.8	9 - 16	01-91	120	29	57	-26	203072	~	4	70 40	7	-15	ř	134	42	39	-31	202628
MLA SB	-	=	30	.,	'n	7	4 29		-16 -10	611 0	7 27	0.9	1 -26	203221	n	•	5.5	99	5	6	134	42	30	-31	202628
ANT SB	-	=	32	-,	un un	‡	30	91-0	01- 91	127	4.8	36	6 -24	202225	r	•	\$	7	-15	6	48	5	•	-26	201979
BDA SB	-	Ξ	32	.,		#	4 32		-16 -10	135	3 35	4.5	- 35	202764	٣	•	9 9	•	5	6	153	‡	. 52	, 04-	202521
ASC SB	-	11	3.	•		Ŧ	1. 0.		-17 -9	16- 4	7 75	5 + 15	.5	201445	n	•	5	<u>+</u>	9	- 6	- 9	88	-32	7.	202024
CY1 SB	-	=	35	••	ď	-	4 42		-17 -10	651-0	9 50	11- 0	1 -37	202119	r	•	26	1.7	-	6	-137	42.	-37	-33	202621
MAD DS	-	=	3.5		so.	7	9 7		-17 -10	641- 0	34	t 52	2 -25	202805	m	•	9	21	91-	2	-132	11	53	-42	203396
GYM SB	0	5	38	.,	9	5	4 17		-16 -10	104	.r.	9 6 5	-14	203730	e	•	2	5.5	÷	0.7	-132	27	53	* 42 ,	203396
50 019	0	717	20	•	~	34	4 34		-15 -10	105	n.	5 72	2 74	203522	e	•	5	3.	•		-132	27	53	-42	203396
GYM SB		=	4		, m	42	2 31		-15 -9	9 1 1 8	8 26	19 9	1 -25	203546	m	00	4	11	7	6	131	•	7	-3.	203052
TEX SB	-	=	5.1		~	4 2	2 31		-15 -9	9 128	8 36	47	7 -30	203026	m	•	\$	22	-	6	45	41	7.8	-34	202697
90 019	-	=	4			4.2		32 -1	-15 -10	116	9 1 9	20 24	59	203991	e	00	\$	8	7	ô	145	41	78	134	202697
681 58	4	=	L+ 1			7	42 3	39 -	-15 -9	9 148	4.9	9 25	5 - 34	1 202474	e	60	5.4	56	-15	6	174	4.	ın	-35	202431
ANT SB	-	=	4,	_	· •	*	42 4	42 -	6- 91-	9 171	1 63		92- 5	201985	n	30	\$	29	-15	6	-152		Ŧ.	-25	202217
MLA SB	-	=	1 #2			4.5		43 -1	15 -9	9 1 4 6	4 4 6	6 29	9 -35	5 202583	e	•	2	25	-15	î	-152	7	¥	*25	202217
BDA SB		=	£# 1		 m	*	4 2 4	00 27	-16 -10	0 1 10	8 7 0		9 -42	202506	e	80	1,	3	-15	î	-165		-13	7	202485
ASC SB	-	Ξ	*	_		*	42 5	52 -	6- 91-	9 - 95	4 6	6 -43	3	1 20253	e	80	4	35			- 95	30	0 9 -	*	203529
CY1 58		=	38			*	42 5	5.8	-16 -9	9 -126	9 34	4 -50	0 -29	203088	e	₩.	3.	36	-15	•	-113	77	-6.7	-22	203950
HAD DS	-	=	39			*	43		-16 -10	0 -122	2 19	9 57	7 -53	3 203885	e	00	4	39	-15	ę.	-109	•	67	69.	204734
IA# SB		=	- F		· ·	*	2 0	5.5	6- 51-	+01 6		1 79	41- 6	1 204661	9	2	52	5	-13		112	7.	9	-20	203955
EYM SB	-	=	34	_		*	_	7	14 -9	9 143	9 * 6	90	-34	1 202848	e	01	52	37	<u>.</u>	0	167	53	•	-36	202752
6L0 05	-	Ξ	34	_	~			· ·	-14 -9	141	1 37	4 4	31	203252	e	01	5.2	39	*		191	*	*	<u>±</u>	203090

TABLE VI.- MISSION RADAR TIMELINE - Continued
(c) 5° minimum elevation - Continued

VEHICLE	-	RADAR TABLE	¥ _	BLE																					
	TRA	TRACKING TIME	- ·	ă A			S	TAT10	STATION ACQUISITION	1510	110N	DATA	<					•	STATION		TERMINATION		DATA		
	ī	NI N NI N	N SEC		DAY H	S.	212	SEC	A 0	DEC	٧Z	ELV	×	>	RANGE	DAY	E S	Z E	SEC	A A	DEC	A2 E	ELV	×	RANGE
TEX SB		-		0 1	М	•	Ŧ	•	-15	٠	162	52	<u> </u>	-36	202619	п	10	52	4	7	0	-170	53 -	-7 -36	202738
		=		37	e	۰	.	Ξ	-15	•	-171	25	-1	-37	202605	n	-	52	47	7 .	9	-146	47 -28	9 - 34	202986
		- -	-	36	r	٠	7	13	• ! 5	6	991-	£.	-10	-35	202553		10	5.2	4	1	9	1 4 1	47 -30	0 -32	202979
ANT SB		-	-	39	6	۰	7		-15	÷	-134	4	-27	-24	202528	3	0.	52	52	-	œ •	-118	41 -45	5 -21	203235
BDA SB		_	-	0+	r	•	÷	7	-15	÷	-149	T	-2B	5.0	202941	•	10	5.5	53	-	9	-131	35 -48	8 -32	203542
ASC SB		0 55		1.6	М	٠	7	1 5	9	6 0	96•	8	-72	9	204251	e	0 1	36	3.4	÷	8	-131	35 -48	8 -32	203542
CY1 SB		0 33		59	r	•	∓	7.1	-16	6	-107	12	●78	9 ! •	204596	~	01	15	70	7	9	-131	35 -48	8 -32	203542
HAW SB		-		4.2	•	=	39	co	-13	9	6 : 1	36	5.0	-23	203585	•	12	20	20	-12	3	134	e +	32 -27	203169
GYH SB		-		38	•	11	39	7	1		-173	5.3	.s	-36	202846	n	12	5	~	-13	9	-147	49 -26	PE - 91	203207
90 019		-		36	~	Ξ	39	25	+	6	177	\$	3	7	203123	e.	1.2	5.1	-	-13	00	-147	- 64	-26 -34	203207
TEX SB		-	_	3.8	n	Ξ	39	56	*	8	-152	20	-22	-35	202969	r	12	5 1	7	-13	3	-131	41 -41	1 -30	203531
GB1 SB		-	_	3.8	m	=	39	31	1 4	Φ.	-129	•	-43	-29	203402	e.	12	5.1	30	-13	8	-115	27 -6	-61 -22	20421
MLA SB		-	_	36	•	=	39	32	7	8	-132	3	7	-3	203380	٣	12	5.1	•	-13	9	• - -	28 -	-59 -24	204160
ANT SB		-	_	34	n	=	39	35	-15	œ.	-111	31	-57	1.8	203823	•	12	5 1	D	¥7-	8	-103	91	-74 -13	204857
BDA SB		-	-	34	m	Ξ	39	36	* -	90 1	-121	27	0.9-	-27	504049	7	12	5.1	D	1 1	3 0	601-	· ·	-75 -18	204950
CNB DS		0 37		£.	n	12	12	25	-13	•	9.5	S	\$	83	204069	~	12	20	37	¥1-	æ •	-109	1 2	81- 54-	204956
CNB 05		-	*	36	e	:	37	8 7	-12		83	22	30 4	67	204617	6	*	3,	12 2		•	7.1	35	-26 51	204071
GUM SB		-	_	3.1	м	13	37	52	-12	80	102	15	75	=	166402	e	*	4	26		-1	101	31	58 -14	204254
HAW SB		-	-	7	e	13	37	3.5	-13	8	150	26	-	-29	203034	e	-	4	-	-12	•	-178		-1 -29	203067
90 079		-	-	5+	٣	13	37	3	-13	89	-144	4	4	-27	203677	er.	<u>-</u>	4	30	-12	-1	-127	30	46 -44	204328
67 # SB			_	7	М	13	3,	4	-13	6	-133	4 2	-39	-31	203584	e	<u>.</u>	4	30	-12	-1	-118	30	*57 -24	204355
TEX SB		-	_	47	•	13	37	41	-13	ep	-121	32	-54	-26	204027	9	<u>*</u>	4	4	-13	-	601-	6	-70 -18	146402
MLA SB		_	۰	31	•	13	37	4 0-	-14	\$	-110	19	-70	61-	204765	•	=	47	6.	-13	-1	-109	6	-70 -18	204944
GB 1 SB		-	_	-	•	13	37	4	7		-108	11	-72	-	204847	7	*	38	95	-13	-1	-109	6.7	-70 -18	204944
CAR SB		0	e	<u>د</u>	e	<u>+</u>	.	33	7	9	9	រោ	85	i.	205550	~	-	4.	£ 20	-13		-109	<u>•</u>	-70 -18	204944

TABLE VI.- MISSION RADAR TIMELINE - Continued (c) 5° minimum elevation - Continued

11 13 3 15 35 2 11 -7 0 14 74 0 205201 3 16 47 11 13 3 15 35 3 -1 -7 0 14 74 0 205201 3 16 47 11 13 3 15 35 3 -1 -7 0 14 74 0 205201 3 16 47 11 13 3 3 15 35 3 -1 -7 11 3 44 -1 203864 3 16 47 11 3 3 15 35 3 -1 -7 11 3 44 -1 203864 3 16 47 11 3 3 15 35 44 -1 -7 11 3 44 -1 203864 3 16 47 11 3 16 47 11 3 3 16 3 44 -1 -7 11 3 44 -1 2 203865 3 16 47 11 2 2 2 2 2 2 2 2	1 RADA	RADAR TABLE	m			·	;	•								Š	AT 10	1 E	YN I W	S-ATION TERMINATION DATA	DATA		
SEC DAY HES NIN SEC R. A. DEC AZ ELV X. Y. RANGE DAY HES NIN SEC RADE AZ ELV S. Y. RANGE DAY HES NIN SEC RADE AZ ELV S. Y. RANGE DAY HES NIN SEC RADE AZ ELV S. Y. RANGE DAY HES NIN SEC RADE AZ ELV S. Y. D. S.	Z	G TIME				STAT	¥ NO	20.0	N 1 1 1 1 1 1 1	V V V	_								į		-		
13 15 15 15 17 -11 -1	-		DAY				A A	DEC		EL V	×	>	RANGE	DAY								٠ ;	•
31 15 35 37 -11 - 6 40 44 627 39 203802 3 16 47 11 -11 - 6 10 34 - 7 - 12 - 12 - 12 - 12 - 12 - 12 - 12	-		e	5			=	-	90	•	*		102502	n	9.	+	Ŧ	2	•	! D :			
1 3 3 4 -11 -7 113 42 44 -12 20344 3 14 7 1 -10 -7 124 57 -24	-	34	3	5			==	1	9		27		203602	•	<u>:</u>	+	=	=	•	2			
1	_		•	5					113	4			203864	•	9	4	1.7	01:		126			
	-	1 30	•	-			-12	-1	-155				203248	7	9.	4,7	31	=		181			
11 26 3 15 36 10 -13 -7 -103 9 -81 -13 205605 3 15 55 16 -12 -7 -104 10 68 -72 11 1 26	_			-			-13		-117	22			204851	e	•	41	37	-15		901.			
TELICNITION TELIC	_		.,	-				-7	-103				509502	æ	5	5	•	-15		901-			
57 27 3 17 21 14 -10 -6 77 39 50 10 20400 4 2 18 41 -12 -6 -74 5 -85 -4 4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 2 -12 -6 -74 5 -85 -4 4 0 1 2 -12 -6 -74 5 -85 -4 4 0 1 2 -12 -6 -74 5 -85 -4 1 0 1 2 -12 -6 -74 5 -85 -4 1 0 1 2 -12 -6 -74 5 -85 -4 1 0 1 2 -12 -6 -74 5 -85 -4 1 0 1 2 -12 -6 -74 5 -85 -4 1 0 1 2 -12 -6 -74 5 -85 -4 1 0 1 2 -12 -6 -74 5 -85 -4 1 0 1 2 -12 -6 -74 5 -85 -4 1 0 1 2 -12 -12 -12 -12 -12 -12 -12 -12 -12	-	11 26	.,	=					• : :0			6	204952	n	•	47	37	-13		101			
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36 1 21 </td <th>•</th> <td>· •</td> <td>•</td> <td></td> <td>7 21</td> <td></td> <td></td> <td>9</td> <td>7 7</td> <td></td> <td>-29</td> <td></td> <td>204166</td> <td>3</td> <td>0</td> <td>-</td> <td>22</td> <td>-12</td> <td>•</td> <td>*</td> <td></td> <td></td> <td></td>	•	· •	•		7 21			9	7 7		-29		204166	3	0	-	22	-12	•	*			
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19 42 3 23 25 26 -10 -7 101 5 65 -11 199208 4 10 30 21 -12 -6 -96 5 -85 -11 199208 4 10 30 21 -12 -6 -96 5 -85 -11 199208 4 10 30 21 -12 -96 5 85 -11 199208 4 10 30 21 -12 -96 5 85 -11 199208 4 10 30 21 -12 -96 5 85 -11 199208 4 10 30 21 -19 -96 5 85 -11 199208 4 10 30 21 11 4 12 21 -10 7 100 5 85 -11 194097 4 14 42 58 -11 -11 41 41 41 41				3	-				10	'n	70	75	199832	Ŧ	0-	31	•	=		101-	•		
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36 52 4 12 25 28 -9 -6 93 5 34 84 183656 5 0 2 19 -10 -5 -92 5 26 -84 1 24 4 13 1 30 -9 -6 98 5 85 -8 182840 5 0 2 54 -10 -6 -97 5 -85 97 30 46 4 14 50 33 -9 -6 94 5 85 -4 180330 5 2 21 19 -10 -5 -93 5 -85 -3	0			*	9	*	7			'n	9	•	187643	•	20	=	52	=	9	66-		- 85	
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	=		•	-							9			vA	8	2.1	61	-	ů.	-93		9	

TABLE VI.- MISSION RADAR TIMELINE - Continued (c) 5° minimum elevation - Continued

VEHICLE I RADAR TABLE

	TRAC	N 1 N 6	TRACKING TIME				STAT	NOIL	COUL	STATION ACQUISITION DATA	L DA1	₹						STATE	NO T	ERM 1	STATION TERMINATION DATA	IV	.		
	S.	Z Z	SEC	DAY	E S	Z I	SEC	¥ ¥	DEC	Z V	FLV	×	>	RANGE	DAY	S.	Z	SEC	æ	330	7 Y	ELV	×	> -	RANGE
MAD DS	0	2.1	53	7	23	1 2 1	61	8	9	103	ų	9 9	16	145291	'n	•	4 6	12	6.	9	-102	ď	67	-77	146311
ASC SB	Ξ	20	r	*	23	31	£	80	5	9 5	S	85	3	167264	3	9	5.1	*	6	Š	+6-	ď	6.5	*	147094
CY1 58	01	2	2. ru	*	23	55	12	8 0	9	100	'n	9 2	=	166629	S)	10	4	56	î	ŝ	* 6 -	S	15 15	*	147094
ANT SB		0	01	'n	7	53	34		•	9.6	S	8	5 0	161679	w	13	53	4	9	\$	-97	ıß	8.5	-	140979
BDA SB	10	3.9	χ. \$	Ŋ	m	- 15	.s		•	100	ď	8	-10	160191	ın	13	ŝ	4	9	•	- 9 9	ın	100	6	140907
681 88	10	3 7	5.6	5	*	•		-7	9	•	ď	8 5	6	159596	·s	*	ů,	9.	30	5	86-	S	• 8 5		138844
MLA SB	10	7	77	'n	*	17	16	•	9	66	v	9.5	6	159269	vn	5	•	37	1	S	66.	ß	6.05	•	138538
TEX SB	10	4	•	'n	ú	23	5	-1	Ť	66	ß	9 2	6	157313	s.	1 6	=	4	9	Ş	- 9	ď	- 85	®	136105
GYM SB	0.	4	-	ú	•	11	38	-1	•	6	ď	8	Ŷ	185701	ú	17	ū	39	-1	S	-98	ď	-85		134146
50 019	10	36	30	G	•	4.	32	- 1	9	101	'n	9	7.8	154764	īŪ	1.7	25	~	-	1	-100	ū	63	-19	133433
HAW SB	0	5 6	4.7	G	•	30	4	9		9.8	s	85	8	149708	ú	20	27	36	-1	1	-97	ø	58+		126487
CNB DS	-	27	8	ū	12	40	38	•	1	6	Ŋ	13	9	143477	•	0	7	0	•	~	-89	M	-	- 85	117524
GUM SB	=	•	37	ū	13	-	27	9	÷	96	'n	8	Ŷ	142465	•	0	17	5	•	Ť	-95	ß	9	iù.	117116
CAR SB	=	24	25	ū	15	ū	_	\$	Ŧ	9.2	'n	8 5	7	138487	٠.۵	7	29	5.9	Ş	-5	06-	J	1 8 5	0	111339
MAD DS	0	4.0	7	'n	23	29	5		ı,	100	5	4	19	119112	•	0	12	53	7	?	86-	so.	5	9.	98596
ASC SB	=	2.1	90	v	23	37	4	6-	7	93	S	8	7	118321	•	=	•	£	7	ĩ	-90	ď	- 85	•	85454
CY1 S8	-	-	20	4	0	•	38		*	44	s.	8	-	117566	•	=	7	6.0	7	7	- 0	ın	99	0	85454
ANT SB	Ξ	<u>+</u>	=	•		•	5		-3	9.5	ß	8	5	165601	•	-	23	7	7	7	-93	ß	185	7	74081
BDA SB	=	-	51	•	~	28	76	7	Ť	9	'n	8		108700	•	-	30	11	7	?	-95	•	- 9 2	\$	73630
681 58	=	•	1 9	•	*	20	-	-2	*	44	ú	8	-7	106309	•	5	59	37	0	ĩ	+ 9 +	us.	- 85	Ŧ	6 2 8 5 4
MLA SB	=	•	~	•	*	ř	61	-2	1	44	s	8		105795	•	15	39	21	0	7	*6=	s	- 85	Ŧ	49226
TEX SB	=	=	88	•	v	38	4	7		9,6	vı	85	•	102593	•	7	50	11	-	7	*	w	9	Ť	74449
GYM SB	Ξ	13	†	•	•	33	24	7		96	'n	85	•	99938	•	1.7	4	•	7	0	-93	s	- 85	ĩ	42509
50 019	=	90	6.	•	^	7	53	7	-3	9 6	S	5.7	8	98477	•	8 7	=	13	7	7	* 6 -	s	F	-63	58793
HAW SB	=	32	2. C	•	•	5	21	-	-5	9 5	ស	8	ı,	89761	•	71	24	•	•	7	-90	•	5	0	43927

TABLE VI. - MISSION RADAR TIMELINE - Concluded

(c) 5° minimum elevation - Concluded

VEHICLE I RADAR TABLE

SEATION TERMINATION DATA	DAY HRS MIN SEC RA DEC AZ ELV X Y RANGE	74440 844 184 2 21 11 11 11 11 11 11 11 11 11 11 11 1						•
STATION TER	SEC RADI	P1 35 t	2 44 -149		2 47 + 149	5 47 +149 5	47 - 17 - 17 - 47 - 47 - 47 - 47 - 47 -	+ + + + + + + + + + + + + + + + + + +
	DAY HRS HIN	7 0 34	7 3 2		7 2 45	7 2 45	7 2 45	7 7 7 7 7 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8
	YRANGE	83 77613	-2 76764		4 68345	26 23400	4 68345 26 23400 33 23400	26 23400 25 23400 25 23400
ON DATA	Z ELV X	15 5 +42	2 5 85		5 85	6 5 85 5 4 ₀ 45	16 5 85 15 40 45 16 39 -42	16 5 85 15 40 45 16 39 -42
STATION ACQUISITION DATA	RA DEC A	3 - 6			- s	5 1 6 24 12 5	5 1 8 24 12 5 16 13 14 15 15 15 15 15 15 15 15 15 15 15 15 15	5 1 8 24 12 5 16 13 -4 27 13 6
STATION	HRS MIN SEC RA DEC AZ ELV X Y RANGE	13 25 14 3 1 85 5 042 83 77613	13 39 19 4 -1 92 5 85 -2 76764		15 52 49	15 52 49 5 1 86 5 85 4 68345 0 28 20 24 12 55 40 45 26 23400	15 52 49 5 1 86 5 85 4 68345 0 28 20 24 12 55 40 45 26 23400 0 28 32 16 13 -46 39 -42 33 23400	15 52 49 5 1 86 5 85 4 68345 0 28 20 24 12 55 40 45 26 23400 0 28 32 16 13 -46 39 -42 33 23400 0 36 21 27 13 63 20 68 25 23400
TRACKING TIME	HRS MIN SEC DAY	11 9 21 6	23 26	1	52 58 . 6	52	52 7 1	52 7 17
TRACK	I R	SO WAY	6UM SB 13		CAR SB 10			

TABLE VII.- MISSION SHADOW TIMELINE

(a) Earth orbit phase

[Insertion occurs at 0:00:11:20]

Lighting	Enter, g.e.t., day:hr:min:sec	Exit, g.e.t., day:hr:min:sec
Earth penumbra	0:00:51:33.8	0:00:51:46.1
Earth umbra	0:00:51:46.1	0:01:25:32.3
Earth penumbra	0:01:25:32.3	0:01:25:45.0
Sunlight	0:01:25:45.0	0:02:19:42.4
Earth penumbra	0:02:19:42.4	0:02:19:54.5
Earth umbra	0:02:19:54.5	

(b) Translunar phase

TLI ignition occurs at 0:02:50:31; TLI cutoff occurs at 0:02:55:43

Vehicle is in sunlight throughout translunar phase.

TABLE VII. - MISSION SHADOW TIMELINE - Continued

(c) Lunar orbit phase; LOI to circularization burn

LOI ignition occurs at 2:21:07:29; cutoff at 2:21:11:35; circularization burn ignition occurs at 3:01:30; cutoff at 3:01:31:02

Lighting	Enter, g.e.t., day:hr:min:sec	Exit, g.e.t., day:hr:min:sec
Lunar penumbra	2:22:13:59.3	2:22:14:12.7
Lunar umbra	2:22:14:12.7	2:23:00:13.9
Lunar penumbra	2:23:00:13.9	2:23:00:26.9
Sunlight	2:23:00:26.9	3:00:22:31.4
Lunar penumbra	3:00:22:31.4	3:00:22:46.7
Lunar umbra	3:00:22:46.7	3:01:08:46.3
Lunar penumbra	3:01:08:46.3	3:01:08:59.3
Sunlight	3:01:08:59.3	

TABLE VII. - MISSION SHADOW TIMELINE - Continued

(d) Lunar orbit phase; circularization burn to TEI

Circularization burn ignition occurs at 3:01:30:53; cutoff at 3:01:31:03

Lighting	Enter, g.e.t., day:hr:min:sec	Exit, g.e.t., day:hr:min:sec
Lunar penumbra	3:02:22:45.0	3:02:22:56.1
Lunar umbra	3:02:22:56.1	3:03:08:53.4
Lunar penumbra	3:03:08:53.4	3:03:08:56.9
Sunlight	3:03:08:56.9	3:04:21:18.1
Lunar penumbra	3:04:21:18.1	3:04:21:29.3
Lunar umbra	3:04:21:29.3	3:05:07:25.4
Lunar penumbra	3:05:07:25.4	3:05:07:36.4
Sunlight	3:05:07:36.4	3:06:19:53.6
Lunar penumbra	3:06:19:53.6	3:06:20:02.3
Lunar umbra	3:06:20:02.3	3:07:05:59.0
Lunar penumbra	3:07:05:59.0	3:07:06:10.4
Sunlight	3:07:06:10.4	3:08:18:32.4
Lunar penumbra	3:08:18:32.4	3:08:18:43.8
Lunar umbra	3:08:18:43.8	3:09:04:38.7
Lunar penumbra	3:09:04:38.7	3:09:04:47.4
Sunlight	3:09:04:47.4	3:10:17:06.1
Lunar penumbra	3:10:17:06.1	3:10:17:17.0
Lunar umbra	3:10:17:17.0	3:11:03:13.3
Lunar penumbra	3:11:03:13.3	3:11:03:24.5

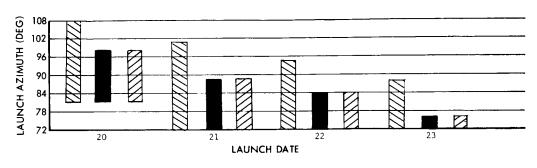
TABLE VII. - MISSION SHADOW TIMELINE - Concluded

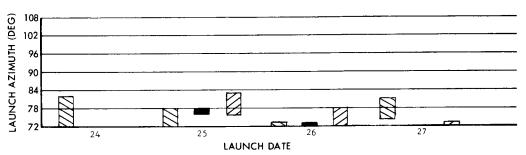
(d) Lunar orbit phase; circularization burn to TEI - Concluded

Lighting	Enter, g.e.t., day:hr:min.sec	Exit, g.e.t., day:hr:min:sec
Sunlight	3:11:03:24.5	3:12:15:37.2
Lunar penumbra	3:12:15:37.2	3:12:15:51.4
Lunar umbra	3:12:15:51.4	3:13:01:46.5
Lunar penumbra	3:13:01:46.5	3:13:01:57.7
Sunlight	3:13:01:57.7	3:14:14:19.6
Lunar penumbra	3:14:14:19.6	3:14:14:30.9
Lunar umbra	3:14:14:30.9	3:15:00:25.9
Lunar penumbra	3:15:00:25.9	3:15:00:40.9
Sunlight	3:15:00:40.9	3:16:12:54.5
Lunar penumbra	3:16:12:54.5	3:16:13:05.2
Lunar umbra	3:16:13:05.2	3:16:59:00.8
Lunar penumbra	3:16:59:00.8	3:16:59:12.1
Sunlight	3:16:59:12.1	
	(e) Transearth phase urs at 3:17:04:02, cutoff interface occurs at 7:03:	
Earth penumbra	7:02:40:25.2	7:02:40:40.2
Earth umbra	7:02:40:40.2	

TABLE VIII.- TRANSLUNAR INJECTION TRACKING SHIP COVERAGE

(a) Coverage and ship locations for the December 1968 launch window.





LAUNCH AZIMUTH COVERAGE PROVIDED



SHIP POSITIONS

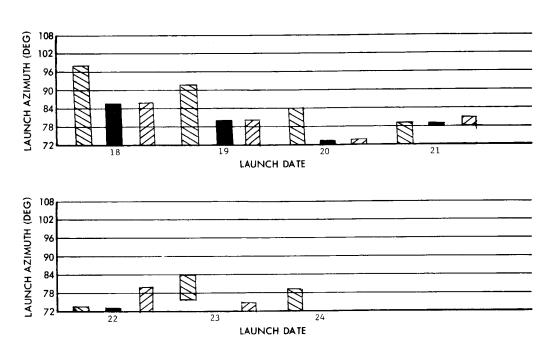
Launch Window Duration

	·	Covered (deg)		For A	zimuths Co (hr:min)	vered		Ship Pos	itions	
							Shi	p l	Shi	ip 2
Launch Date	Second Rev	Common	Third Rev	Second Rev	Common	Third Rev	Lat (deg)	Long (deg)	Lat (deg)	Long (deg)
20 Dec	81-108	81-98	81-98	3:55	2:06	2:06	11.0N	179.0E	7.ON	157.0E
21 Dec	72-101	72-89	72-89	3:45	2:00	2:00	7.5N	178.5W	2.5N	155.5E
22 Dec	72-95	72-84	72-84	3:00	1:27	1:27	2.ON	175.0E	2.5S	148.2E
23 Dec	72-88	72-76	72-76	2:07	0:36	0:36	0.0	171.0E	7.58	148.OE
24 Dec	72-82			1:23			0.0	167.OE	11.08	150.5E
25 Dec	72-78	76-78	76-83	0:52	0:19	1:04	1.08	162.5E	13.0s	146.0E
26 Dec	72-73	72-73	72-78	0:10	0:10	1:00	3.0S	165.0E	17.58	146.5E
27 Dec	74-81		72-73	1:18		0:10	3.0S	165.0E	17.5S	146.5E

NOTE: Tracking coverage from "TLI ignition - 2 minutes" through TLI ignition.

Azimuths

TABLE VIII. - TRANSLUNAR INJECTION TRACKING SHIP COVERAGE - Concluded (b) Coverage and ship locations for the January 1969 launch window.



LAUNCH AZIMUTH COVERAGE PROVIDED



SHIP POSITIONS

		Azimuths Covered (deg)			Window Do zimuths Co (hr:min)			Ship Pos		
Launch Date	Second Rev	Common	Third Rev	Second Rev	Common	Third Rev	Lat (deg)	Long (deg)	Lat (deg)	Long (deg)
18 Jan	72-98	72-86	72-86	3:26	1:34	1:34	4.0N	176.0E	1.0N	150.0E
19 Jan	72-92	72-80	72-80	2:38	0:57	0:57	1.0N	172.5E	3.5\$	148.0E
20 Jan	72-84	72-73	72-73	1:37	0:07	0:07	1.ON	168.0E	10.75	150.7E
21 Jan	72-79	78-79	78-81	1:00	0:09	0:27	2.5S	165.0E	10.78	145.7E
22 Jan	72-73	72-73	72-80	0:10	0:10	1:17	5.5 S	161.0E	11.08	141.0E
23 Jan	76-84		72-75	1:28		0:42	8.5S	159.5E	14.5S	137.5E
24 Jan	72-79			1:26			8.58	159.5E	16.0S	137.6E

NOTE: Tracking coverage from "TLI ignition - 2 minutes" through TLI ignition.

TABLE IX. - POST-TLI EVENTS TIMELINE

Time from a TLI ignition, sec	Time from ${ m TB}_7$, sec	Event	ΔV, fps	Comment
	0	Hold cutoff attitude		
		Initiate LH2 and LOX NPV's		
		Initiate LH2 continuous vent		Propulsive
	20	Command and hold local horizontal		
	150	LOX NPV turned off		
	006	LH2 NPV turned off		
		LH2 PV turned off		
		Initiate maneuver to separation attitude		
	1080	Freeze separation attitude inertially		
1800	1500	SC separation/ELA jettison	п	+X RCS
1805	1505	Coast to 50 ft separation distance		
1855	1555	Mull .5 fps separation rate	.5	-X RCS
1858	1558	Pitch 180° (SC)		5 deg/sec
1894	1594	Wull .5 fps separation rate	v.	+X RCS
1897	1597	Roll left 60° (SC)		5 deg/sec
1910	0191	Station keep, visual observation photography		Range ≈ 70 ft
_				

maneuvers referenced to TB_7 (column 2) are approximate and based on a 300-second TLI burn time. These times will $^{
m a}{
m Th}_{
m P}$ CC maneuver times will be referenced to TLI ignition, the LV maneuvers to TB $_7$. The times of the SC change as TLI burn time changes.

TABLE IX. - POST-TLI EVENTS TIMELINE - Concluded

Comment	Δt = attitude maneuver time + 8-sec RCS			local horizontal retro		90 ± 18 Average dump time ≈ 240 sec		LV safing
ΔV, fps	1.5					90 ± 18		
Event	Initiate evasive maneuver	LH2 NPV turned on	LH2 NPV turned off	Command LOX dump attitude	LH2 PV turned on	Inititate LOX dump command	LOX dump command off	LOX and LH2 NPV's turned on
Time from TB ₇ , sec	2400	3600	4500	6540	7200	1920	8220	8223
Time from a TLI ignition, sec	2700							

maneuvers referenced to ${
m TB}_7$ (column 2) are approximate and based on a 300-second TLI burn time. These times will a The SC maneuver times will be referenced to TLI ignition, the LV maneuvers to TB $_{7}^{\cdot}$. The times of the SC change as TLI burn time changes.

TABLE X.- TARGET LOADS FOR LUNAR ORBIT INSERTION, CIRCULARIZATION, AND TRANSEARTH INJECTION

[Propulsion system - SPS; guidance - external ΔV]

REFSMMAT

64877632	.076384120	75713590
66111865	54928435	.51108595
37684405	.83213712	0.40686164

Targets

Parameter	LOI	Circularization	TEI
Tig, hr:min:sec, g.e.t.	69:07:29.17	73:30:52.80	89:04:01.86
ΔV_{x} , fps	-2977.2	-138.5	2836.9
ΔV_y , fps	+232.5	0	28.8
$\Delta V_{_{ m Z}}$, fps	+166.8	0	67.1

Gimbal angles at T

Angle	LOI	Circularization	TEI
IGA, deg	- 161	-178	39
MGA, deg	+5	- 2	3
OGA, deg	0	0	180

TABLE XI.- REFSMMAT AND GIMBAL ANGLES FOR REENTRY

REFSMMAT

		_
.5310936	.76132403	.37192111
016918018	.44838224	89368179
84714425	.46833652	.25101303

Gimbal angles at entry interface IGA, deg -23.5

MGA, deg -0.8

OGA, deg -0.3

TABLE XII.- COMMAND MODULE MASS PROPERTIES

CM	wei	ght	,	lb			•	•	•	•	•		•		•		•	•		•	•	•	•	•	•	•	•	12 215.8
Ce	nter	s c	f	gr	avi	ltz	r i	.n	Αŗ	ol	.lc) C	00	rd	lir	at	e	sy	rst	em	١,	ir	1					
	X_{A}																			•				•			•	1040.68
	Y _A																									•	•	-0.03
	Z_{A}		•		•	•				•	•	•	•		•		•	•	•	•		•	•	•	•	•	•	5.91
Mo	ment	s c	f	in	er	tia	a,	sl	Lue	g–f	:t²	2																
	IXX																											5817
	I_{YY}																	•										4985
	T _{ZZ}				•		•					•				•		•				•	•	•	•	•	•	4506
Pr	oduc	ts	of	i	ne	rt	ia	, :	slı	ug.	-f	t²																
	IXY																											46.6
	I _{XZ}							•														•						-403.0
	-XZ	;	•	•	•	-																						07 1

27.4

TABLE XIII.- CONDITIONS AT ENTRY INTERFACE

Elapsed time from launch, hr:min:sec 171:05:31.7
Inertial velocity, fps
Inertial flight-path angle, deg6.26
Inertial azimuth, deg
Spacecraft geodetic latitude, deg 14.629
Spacecraft longitude, deg
Target geodetic latitude, deg 4.3
Target longitude, deg165.
Altitude, ft

TABLE XIV.- COMMAND MODULE AERODYNAMIC COEFFICIENTS

	ANGLE OF ATTACK UMBER	CD	0.82490	0.85388	0.98725	1,06761
	FICIENTS AT TRIM NCTION OF MACH N	ر	0.23583	0,23953	0.25991	0.31655
	AERODYNAMIC COEFFICIENTS AT TRIM ANGLE OF ATTACK AS A FUNCTION OF MACH NUMBER	a, deg	170.82	167.38	164.68	161.99
C _D	₹ .	Σ	0.20	0.40	0.70	06.0
	*		۸+ ۱۰۵۸	Nei		
	•		>	-		

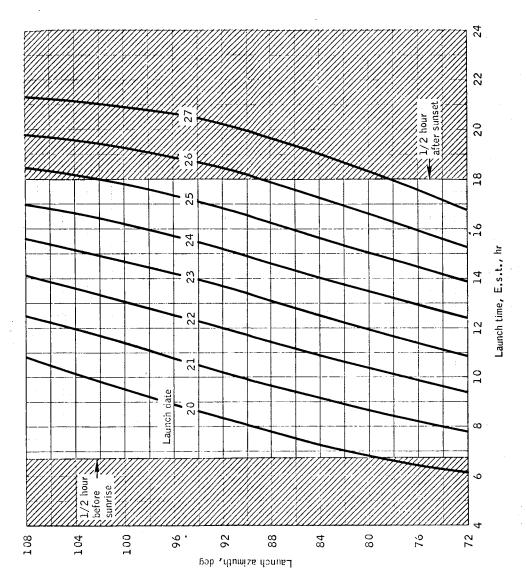
٦/٦	0.28588	0.28054	0,26327	0.29651	0.41498	0.40778	0.43388	0.42986	0.41409	0.40388	0.38867	0.35904	0.34576	0.29638
CD	0.82490	0.85388	0.98725	1.06761	1.17460	1.16020	1,28293	1.26977	1.27861	1,24808	1,22390	1.22038	1.23030	1.29478
CF	0.23583	0.23953	0.25991	0.31655	0.48743	0.47311	0,55663	0.54582	0,52946	0,50407	0.47569	0.43816	0,42539	0.38375
a, deg	170.82	167.38	164.68	161.99	155.27	155.47	154.35	153.54	153.47	153.99	154.47	156.42	157.07	160.36
Σ	0.20	0.40	0.70	06.0	1,10	1.20	1,35	1,65	2.00	2.40	3.00	4.00	10.00	29.50

Center of gravity location in body coordinates $\begin{matrix} X_{cg} = 1040.68 \text{ in.} \\ Y_{cg} = -0.03 \text{ in.} \\ Z_{cg} = 5.91 \text{ in.} \end{matrix}$

$$X_{cg} = 1040.68$$
 i
 $Y_{cg} = -0.03$ in.

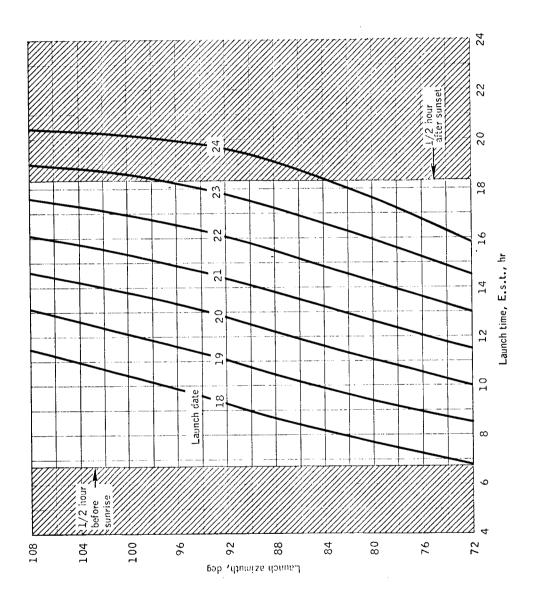
TABLE XV.- ENTRY EVENTS SEQUENCE

Event	Time from lift-off, hr:min:sec	Time from 400 000 ft, min:sec
Reentry	171:05:32	00:00
Enter S-band communication blackout	171:05:59	00:27
Enter C-band communication blackout Load factor = 0.05g	171:06 : 04	00:32
Maximum heating rate	171:06:42	01:10
Guidance initiate at R-DOT = -700 fps	171:06:52	01:20
Maximum load factor (FIRST)	171:06:58	01:26
Exit C-band communication blackout	171:08:36	03:04
Exit 3-band communication blackout	171:09:00	03:28
Maximum load factor (SECOND)	171:11:20	05:48
Termination of CMC guidance	171:12:52	07:20
Drogues parachute deployment	171:13:55	08:23
Main parachutes deployment	171:14:48	09:16
Splashdown	171:19:18	13:46



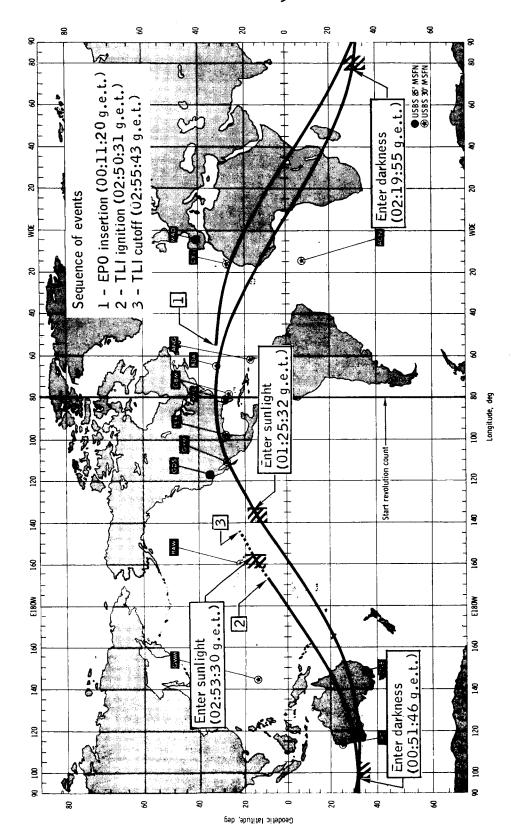
(a) December 1968 launch window.

Figure 1.- Lighting conditions at lift-off.



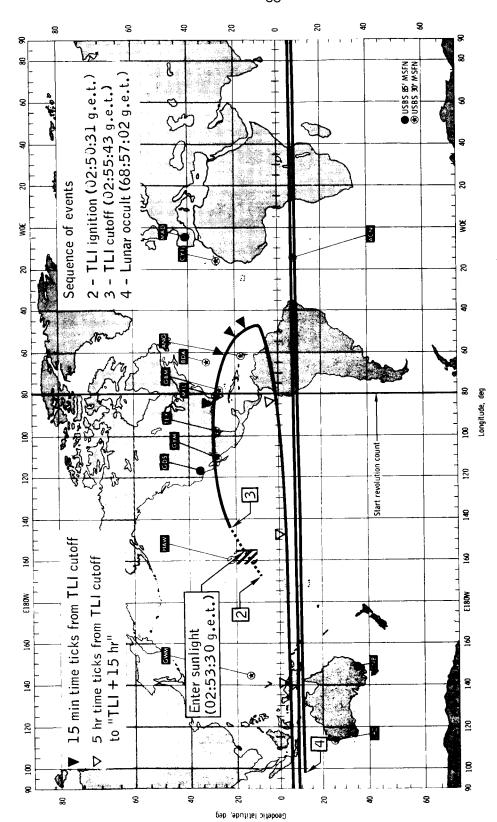
(b) January 1969 launch window.

Figure 1.- Concluded.



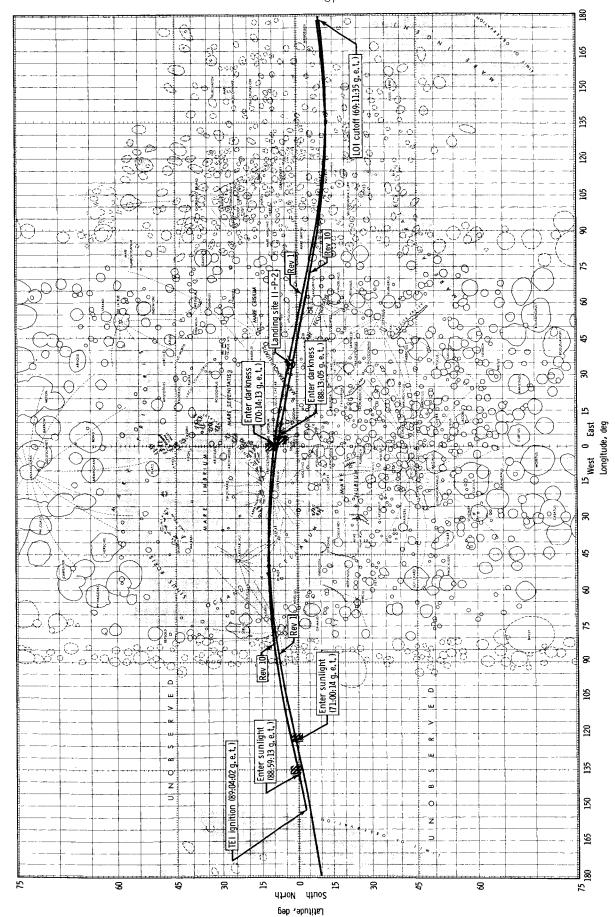
(a) Earth parking orbit.

Figure 2.- Mission ground tracks.



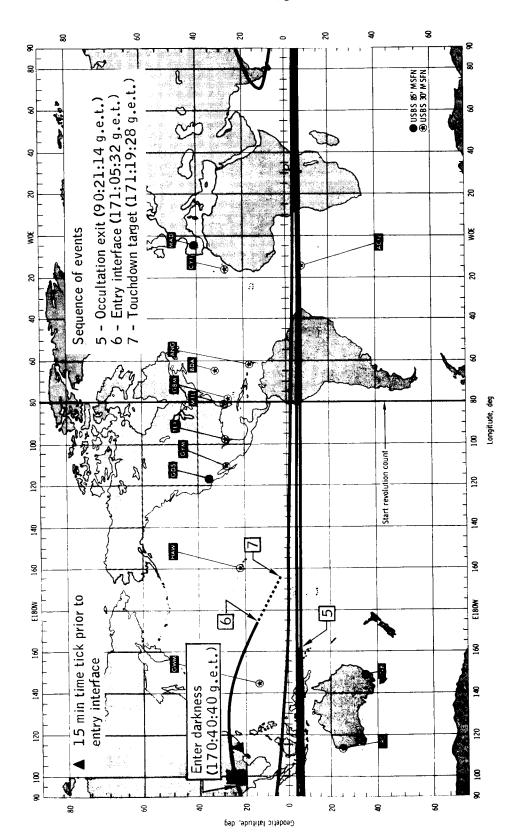
(b) Translunar coast.

Figure 2.- Continued.



(c) Lunar parking orbit.

Figure 2. - Continued.



(d) Transearth coast.

Figure 2.- Concluded.

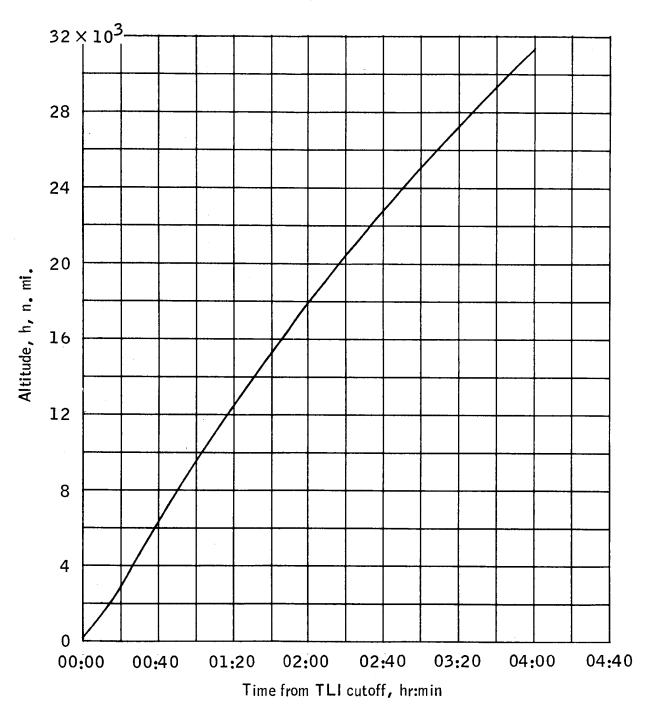


Figure 3.- Time history of altitude for first 4 hours of translunar coast phase.

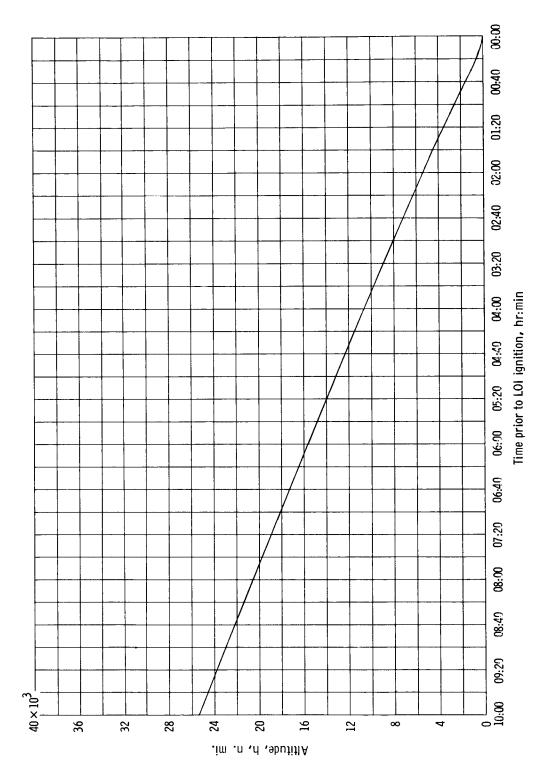
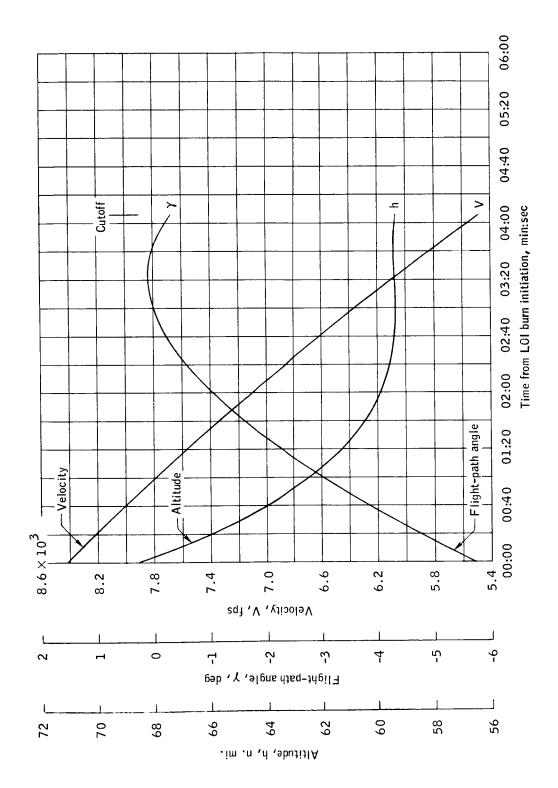
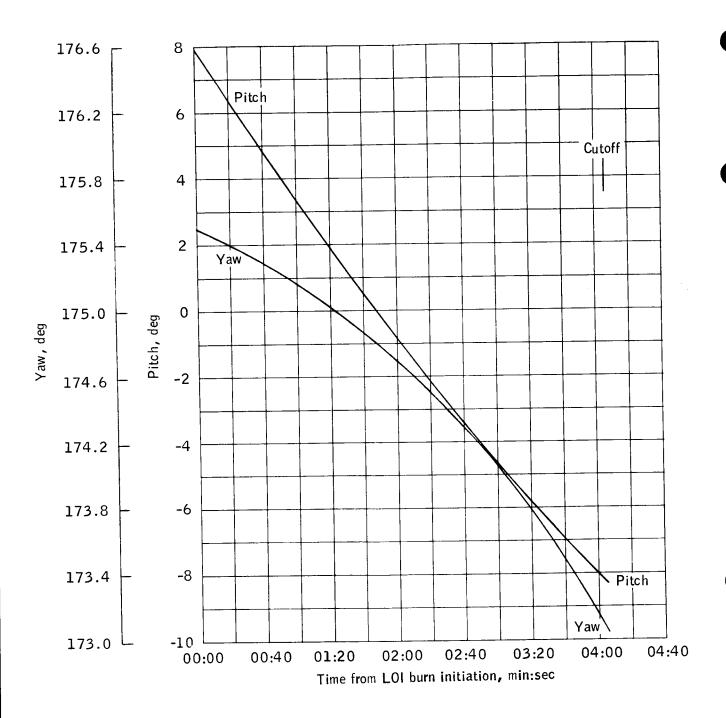


Figure 4.- Time history of altitude 10 hours prior to LOI ignition.



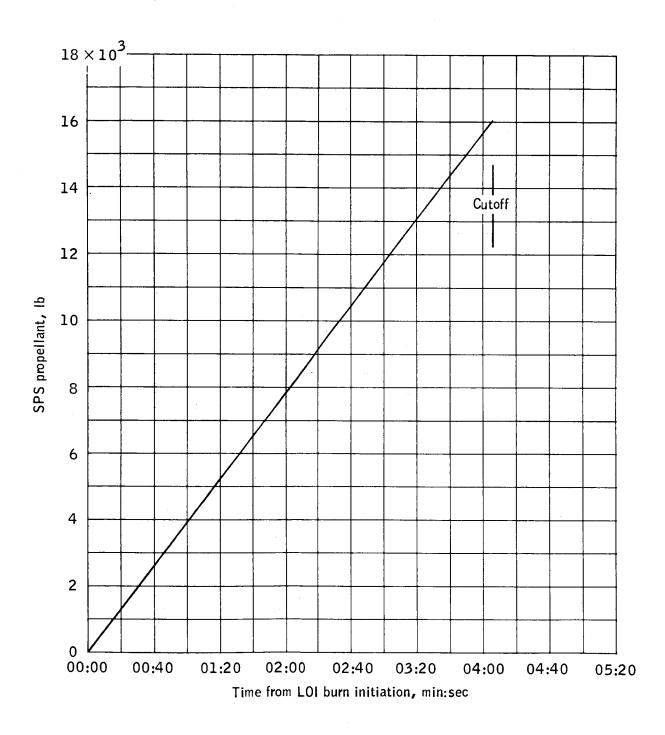
(a) Velocity, flight-path angle, and altitude versus time from LOI burn initiation.

Figure 5.- Time histories of trajectory parameters for the lunar orbit insertion phase.



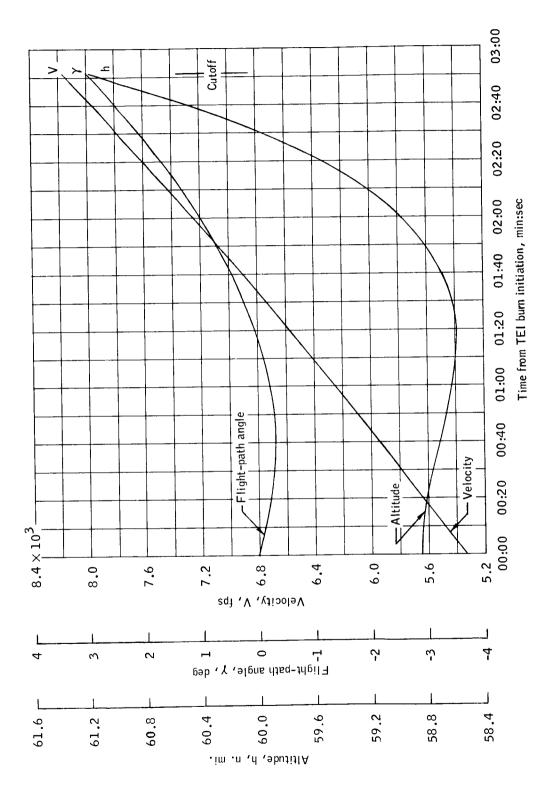
(b) Local horizontal pitch and yaw versus time from LOI burn initiation.

Figure 5.- Continued.



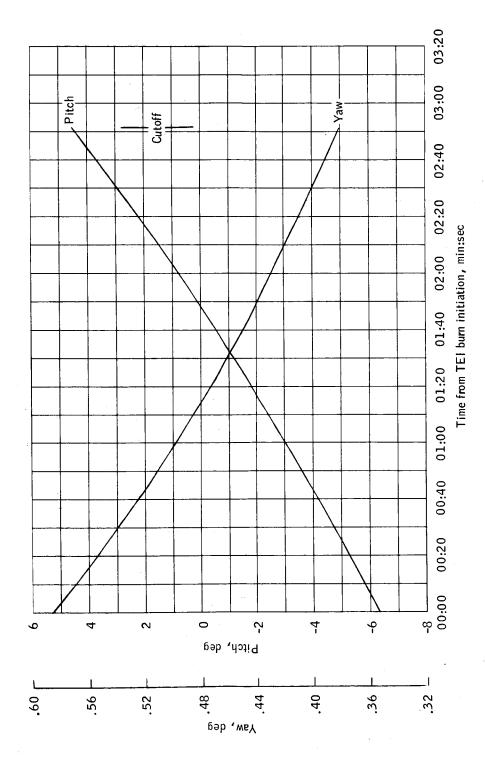
(c) SPS propellant versus time from LOI burn initiation.

Figure 5.- Concluded.



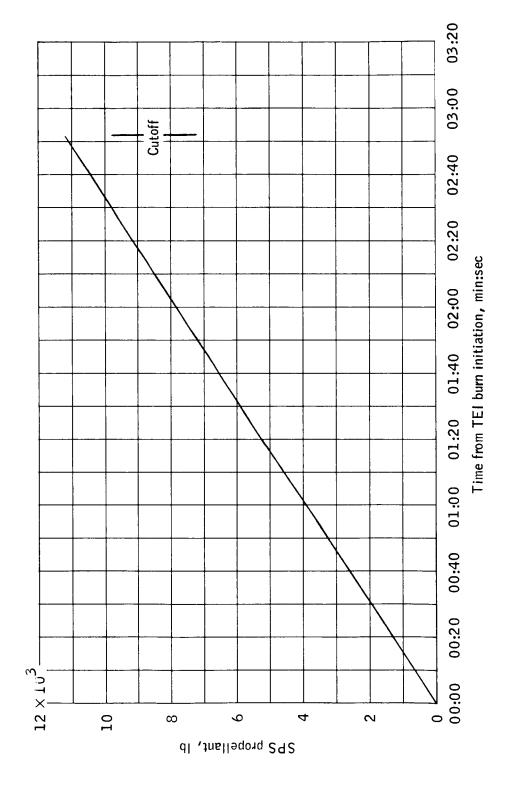
(a) Velocity, flight-path angle, and altitude versus time from TEI burn initiation.

Figure 6.- Time histories of trajectory parameters for the transearth injection phase.



(b) Local horizontal pitch and yaw versus time from TEI burn initiation.

Figure 6.- Continued.



(c) SPS propellant versus time from TEI burn initiation.

Figure 6.- Concluded.

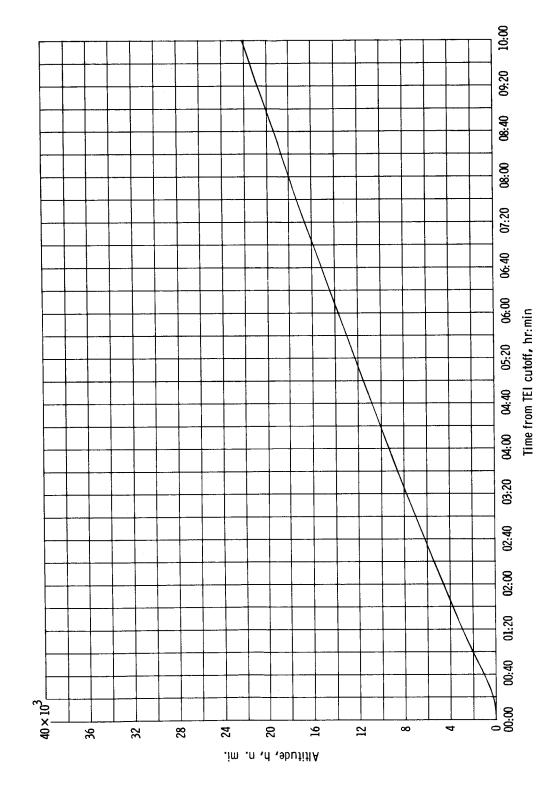


Figure 7.- Time history of altitude for first 10 hours of transearth coast phase.

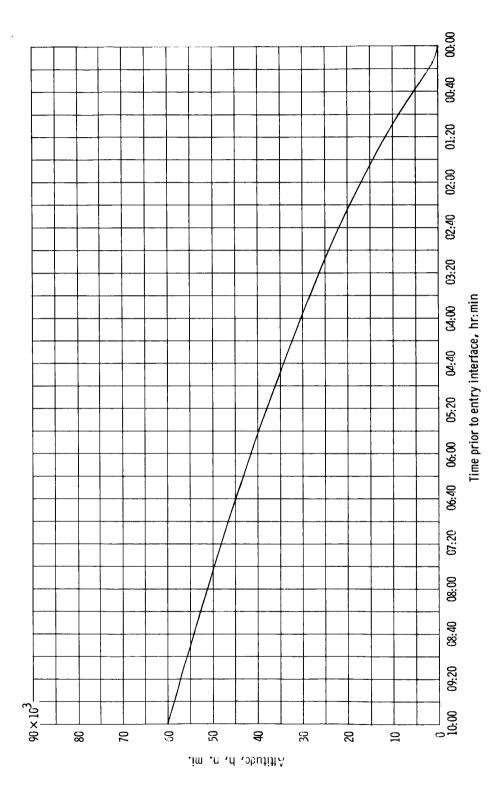


Figure 8. - Time history of altitude 10 hours prior to entry interface.

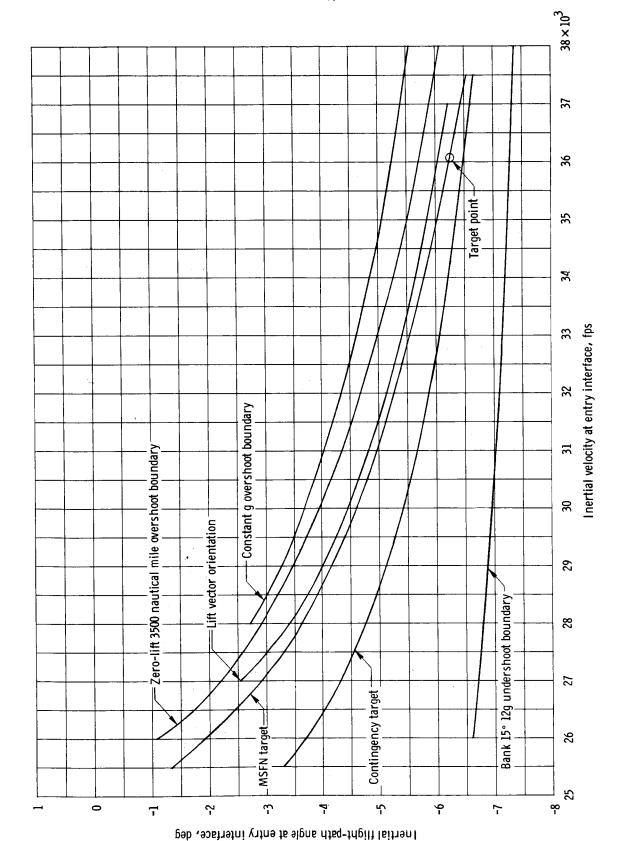


Figure 9. - Reentry corridor.

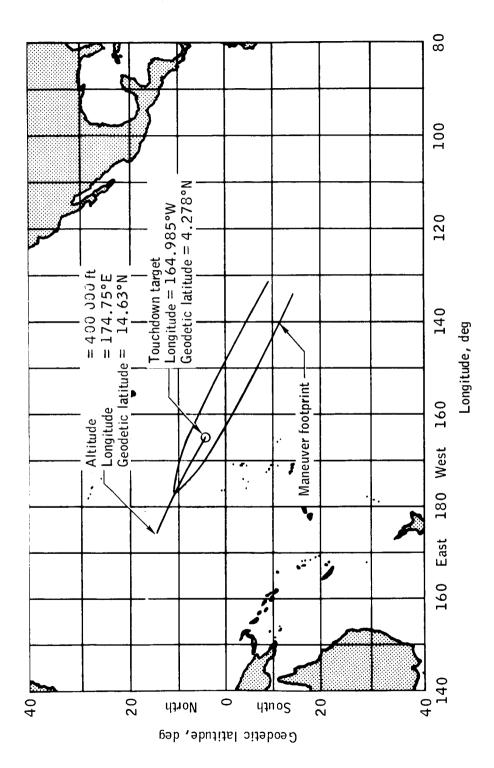


Figure 10.- Maneuver footprint and nominal ground track.

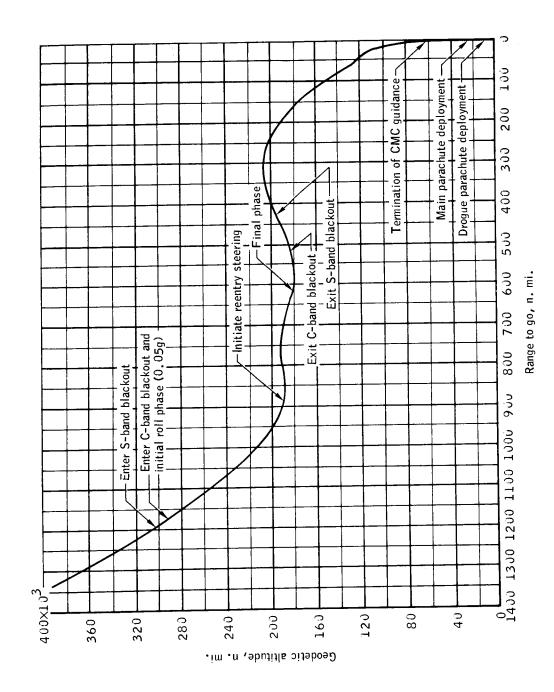


Figure 11.- Geodetic altitude versus range to go.

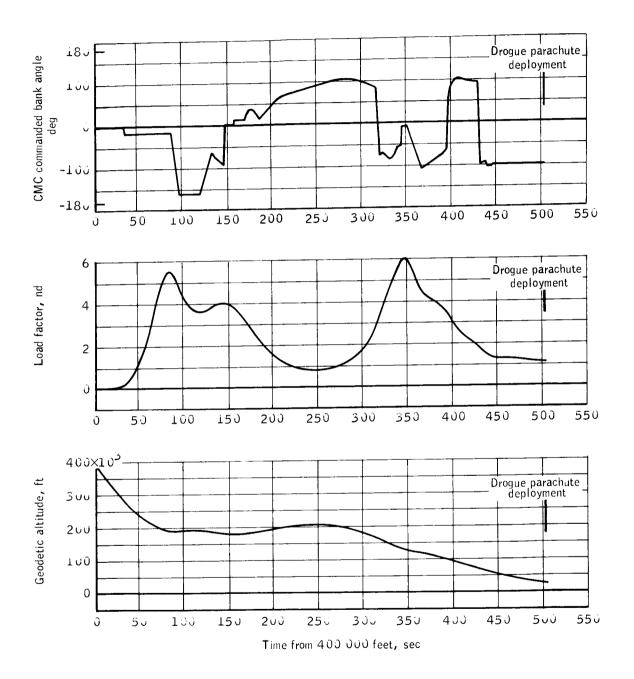


Figure 12.- CMC commanded bank angle, load factor, and altitude time histories.

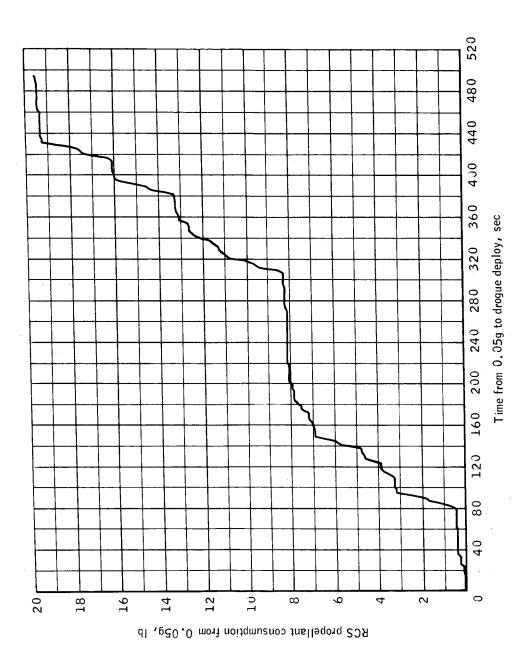


Figure 13.- RCS propellant consumption from 0.05g.

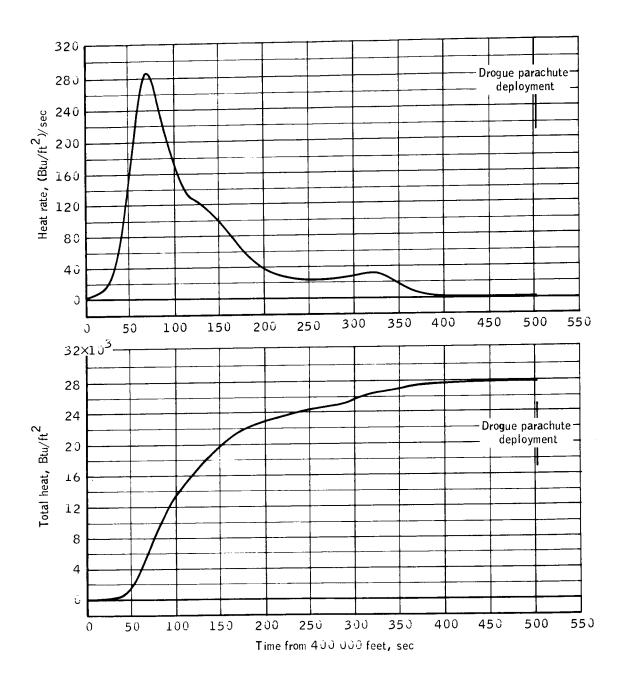


Figure 14. - Aerodynamic heating rate and heat load time histories.

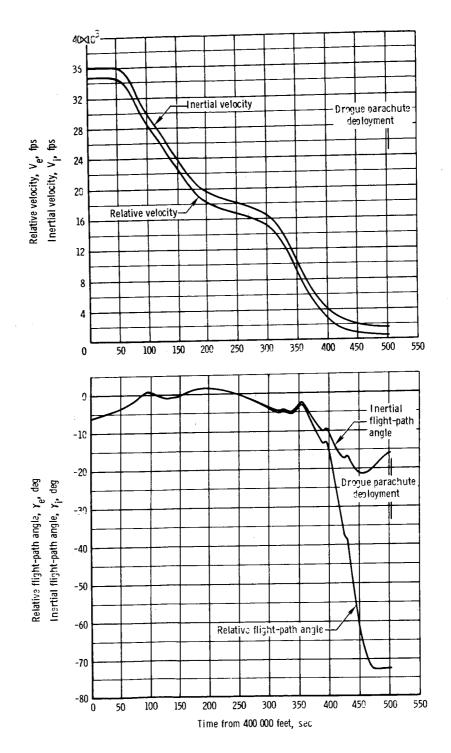


Figure 15. - Reentry velocity and flight-path angle time histories.

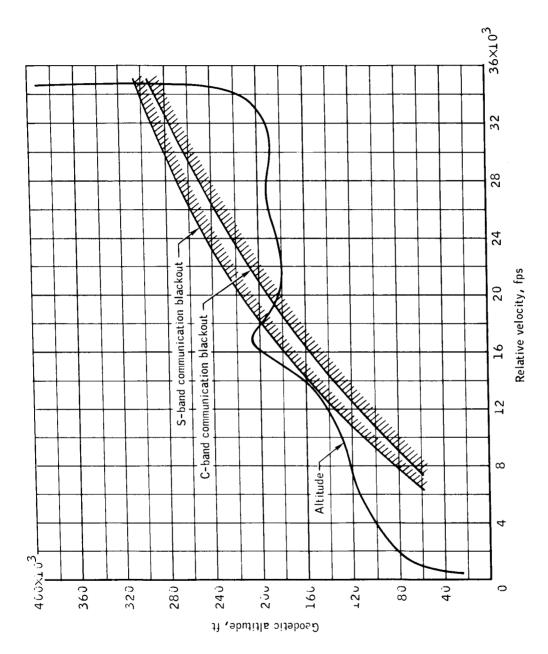


Figure 16.- Communications blackout.

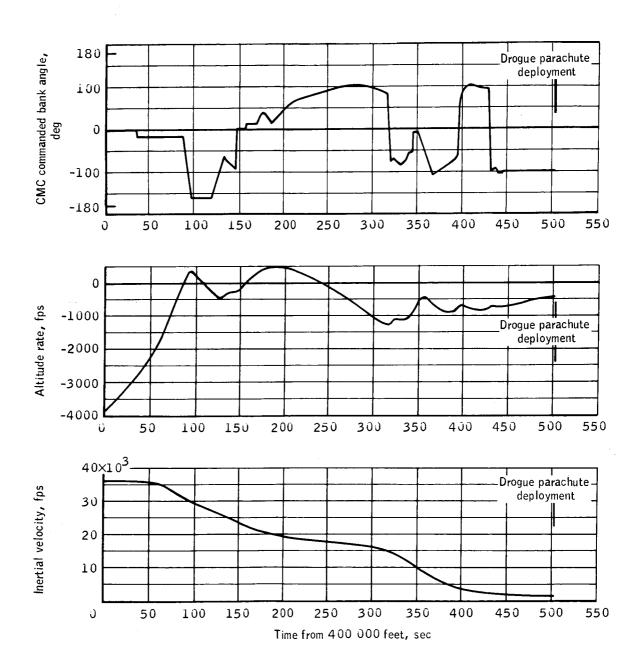


Figure 17.- CMC commanded bank angle, altitude rate and inertial velocity time histories.

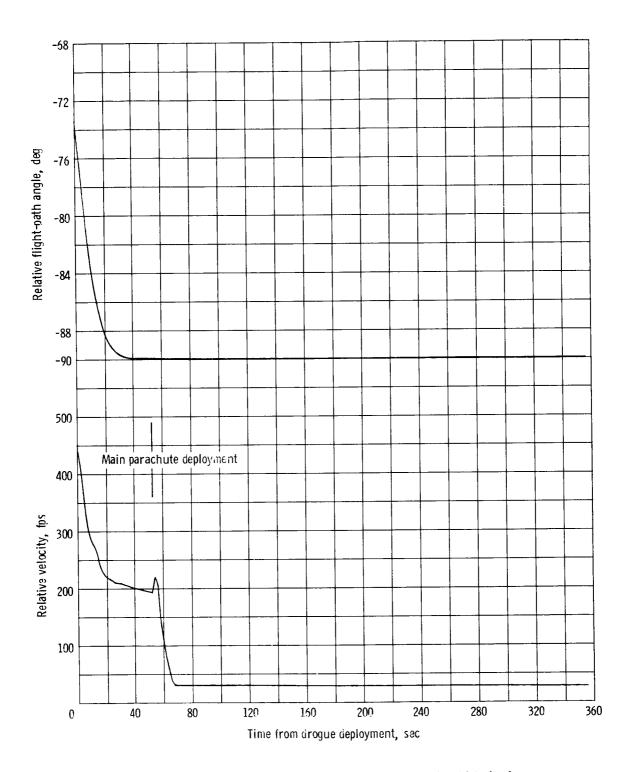


Figure 18.- Relative velocity and relative flight-path angle time histories from drogue parachute deployment.

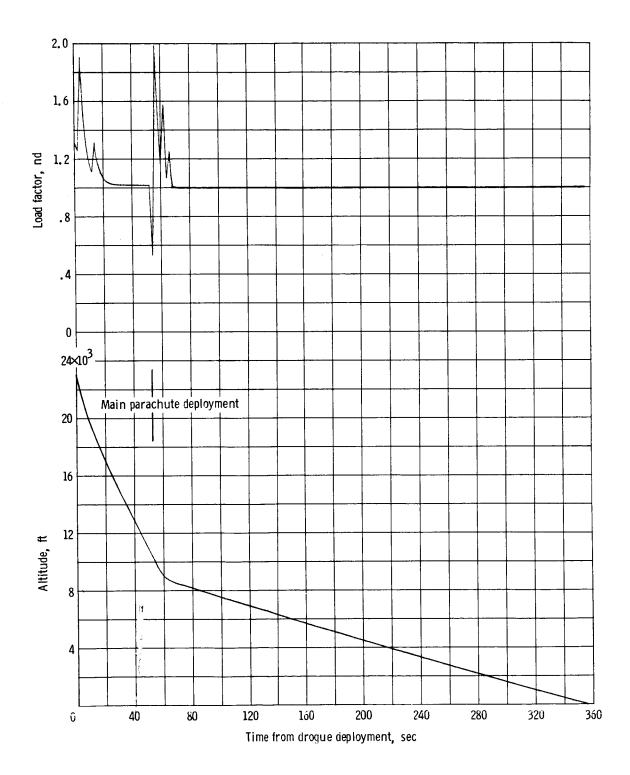
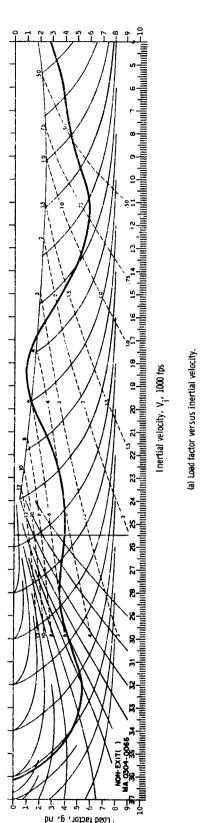
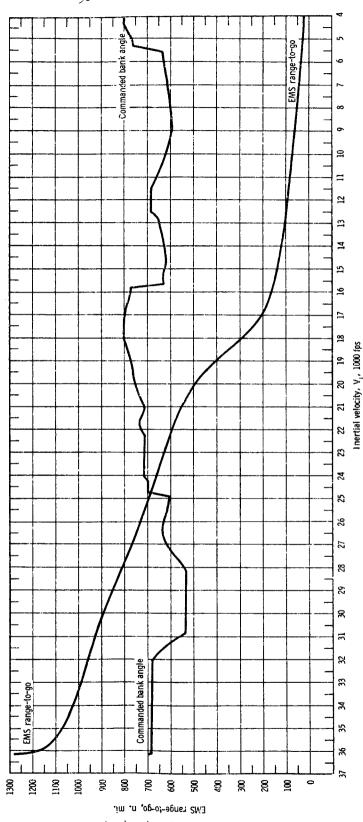


Figure 19. - Altitude and load factor time histories from drogue parachute deployment.





Load factor, g, nd

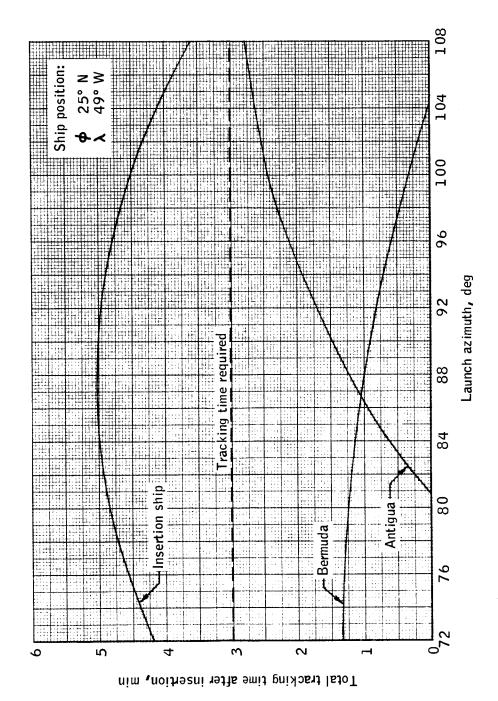


[∓]180 -100

Commanded bank angle, deg

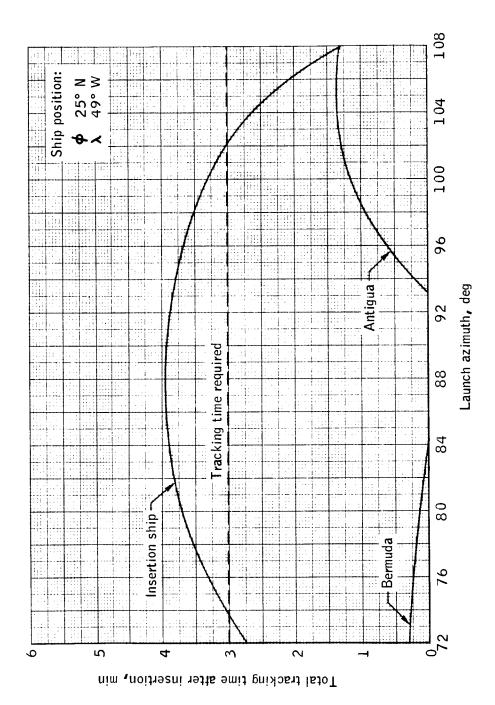
(b) CMC commanded bank angle and EMS range-to-go versus inertial velocity.

Figure 20. - EMS parameters.



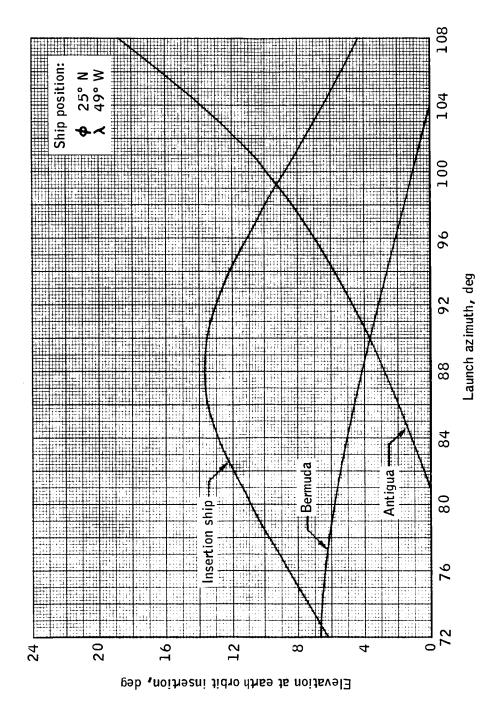
(a) Total tracking time after earth orbit insertion for minimum elevation of $0^{\circ} \cdot$

Figure 21.- Tracking ship locations and tracking coverage.



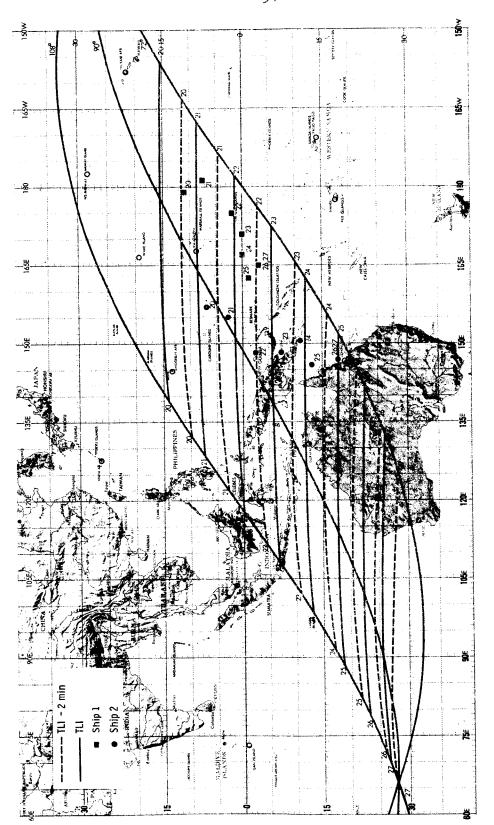
(b) Total tracking time after earth orbit insertion for minimum elevation of 5°.

Figure 21.- Continued.



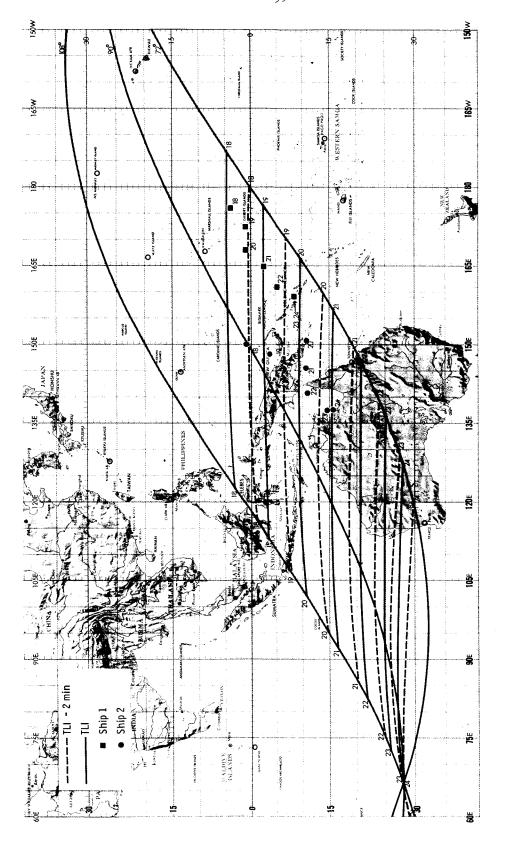
(c) Elevation at earth orbit insertion versus launch azimuth.

Figure 21.- Continued.



(d) Translunar injection tracking ship locations for the December 1968 launch window.

Figure 21.- Continued.



(e) Translunar injection tracking ship locations for the January 1969 launch window.

Figure 21.- Concluded.

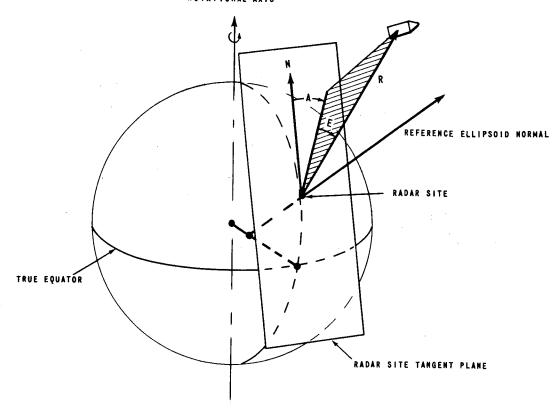
APPENDIX

STANDARD RADAR COORDINATE SYSTEM^a

^aThe coordinate systems definitions were taken from "Project Apollo Coordinate System Standards" reference (16).

STANDARD COORDINATE SYSTEM 3a RADAR (AZ-EL)

EARTH'S TRUE ROTATIONAL AXIS



TYPE:

Rotating, Earth referenced

ORIGIN:

The intersection of the radar axes

ORIENTATION AND LABELING:

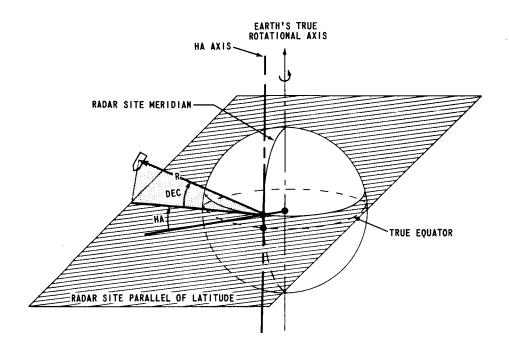
The radar site tangent plane contains the site and is perpendicular to the reference ellipsoid normal which passes through the radar site.

R is the slant range to the vehicle.

A is the azimuth angle measured clockwise from true north to the projection of the slant range vector onto the radar site tangent plane.

E is the elevation angle measured positive above the radar site tangent plane to the slant range vector.

STANDARD COORDINATE SYSTEM 3b RADAR (HA-DEC)



TYPE: Rotating, Earth referenced

ORIGIN: The point of intersection of the hour angle axis with the plane of the declination fear

ORIENTATION AND LABELING:

R is the slant range* to the vehicle.

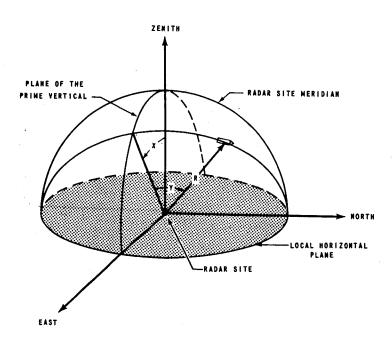
The HA axis is parallel to the Earth's true rotational axis. The declination axis is parallel to the true equator and perpendicular to the HA axis.

The hour ancle (HA) is measured positive westward in the plane of the local radar site parallel of latitude, from the radar site meridian plane to the plane perpendicular to the equator and containing the vehicle and the radar site.

The declination (DEC) is the angle measured from the radar site parallel of latitude to the vehicle, positive north and negative south of this plane.

^{*} Range rate $(\dot{\mathtt{R}})$ data is also generally available in this system.

STANDARD COORDINATE SYSTEM 3c RADAR (X-Y 30 ft,)



TYPE:

Rotating, Earth referenced

ORIGIN:

At the intersection of the X axis and the plane of the Y axis gear

ORIENTATION AND LABELING:

R is the slant range* from the radar site to the vehicle.

The X axis lies along the intersection of the horizontal plane and the meridian plane at the radar site. The Y axis is perpendicular to the X axis.

X is the angle measured in the plane of the radar site prime vertical from the zenith to the projection of the slant range vector onto this plane, positive eastward.

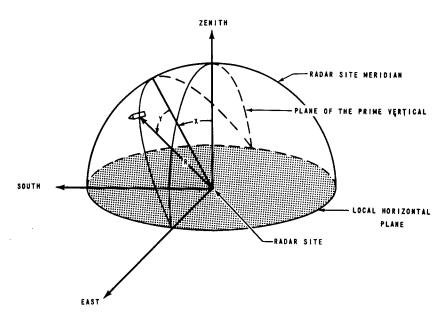
Y is the angle between the slant range vector and its projection onto the plane of the radar site prime vertical, positive when the slant range vector is north of the plane and negative when it is south of it.

(When the radar antenna is directed toward the zenith, the X and Y angles are zero and the Y axis is perpendicular to the radar site meridian plane.)

^{*}Range rate (\hat{R}) data is also generally available in this system.

STANDARD COORDINATE SYSTEM 3d

RADAR (X-Y 85 ft.)



TYPE:

Rotating, Earth referenced

ORIGIN:

At the intersection of the X axis and the plane of the Y axis gear

ORIENTATION AND LABELING:

R is the slant range* from the radar site to the vehicle.

The X axis lies along the intersection of the horizontal plane and the plane of the prime vertical at the radar site. The Y axis is perpendicular to the X axis.

X is the angle measure in the meridian plane of the radar site from the zenith to the projection of the slant range vector onto this plane, positive southward.

Y is the angle between the slant range vector and its projection onto the meridian plane of the radar site, positive when the slant range vector is east of the meridian plane and negative when it is west of it.

(When the radar antenna is directed toward the zenith, the X and Y angles are zero and the Y axis is perpendicular to the radar site prime vertical plane.)

^{*} Range rate $(\hat{\bar{\mathbf{R}}})$ data is also generally available in this system.

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